



Numerical Heat Transfer

(数值传热学) Chapter 4 Numerical Solution of Diffusion Equation and its Applications(2)



Instructor Tao, Wen-Quan

CFD-NHT-EHT Center Key Laboratory of Thermo-Fluid Science & Engineering Xi'an Jiaotong University Xi'an, 2017-Oct-11







第四章 扩散方程的数值解及其应用(2)





西安交通大学能源与动力工程学院 热流科学与工程教育部重点实验室 2017年10月11日,西安





Contents

4.1 1-D Heat Conduction Equation

4.2 Fully Implicit Scheme of Multi-dimensional Heat Conduction Equation

4.3 Treatments of Source Term and B.C.

4.4 TDMA & ADI Methods for Solving ABEs

4.5 Fully Developed HT in Circular Tubes

4.6 Fully Developed HT in Rectangle Ducts



4.4 TDMA & ADI Methods for Solving ABEs

4.4.1 TDMA algorithm (算法) for 1-D conduction problem

- **1.General form of algebraic equations of 1-D** conduction problems
- 2.Thomas algorithm
- 3. Treatment of 1st kind boundary condition
- 4.4.2 ADI method for solving multidimensional problem
 - 1. Introduction to the matrix of 2-D problem
 - **2. ADI iteration of Peaceman-Rachford**



4.4 TDMA & ADI Methods for Solving ABEqs

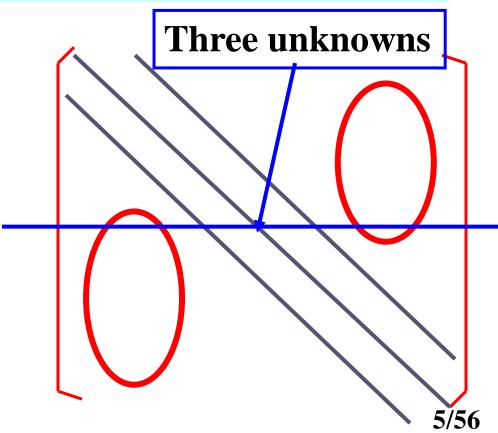
4.4.1 TDMA algorithm for 1-D conduction problem

1.General form of algebraic equations. of 1-D conduction problems

The ABEqs for steady and unsteady (f>0) problems take the form

$$a_P T_P = a_E T_E + a_W T_W + b$$

The matrix (矩阵) of the coefficients is a tridiagonal (三对角) one.



(1) 西安交通大学

2. Thomas algorithm(算法)

The numbering method of W-P-E is humanized (人性化), but it can not be accepted by a computer! Rewrite above equation:

$$A_i T_i = B_i T_{i+1} + C_i T_{i-1} + D_i, i = 1, 2, \dots, M1$$
 (a)

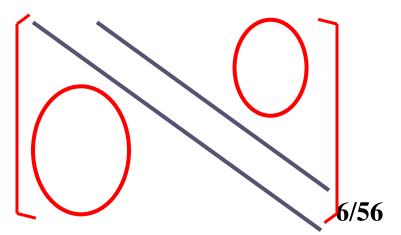
End conditions: $i=1, C_i=0; i=M1, B_i=0$

(1) Elimination (消元)—Reducing the unknowns at each line from 3 to 2

Assuming the eq. after elimination as

$$T_{i-1} = P_{i-1}T_i + Q_{i-1}$$
 (b)

Coefficient has been treated to 1.



1 历安交通大学

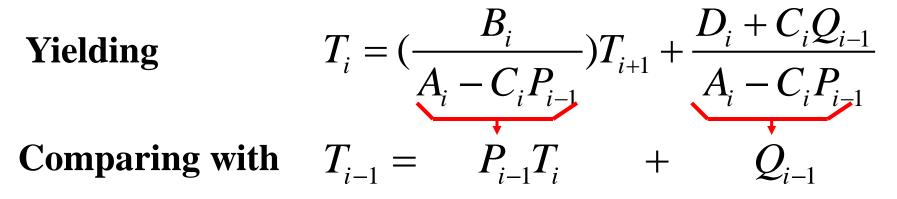
The purpose of the elimination procedure is to find the relationship between P_i , Q_i with A_i , B_i , C_i , D_i :

Multiplying Eq.(b) by C_i, and adding to Eq.(a):

$$A_{i}T_{i} = B_{i}T_{i+1} + C_{i}T_{i-1} + D_{i}$$
 (a)

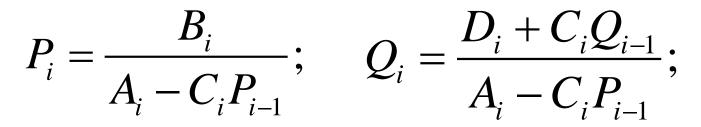
$$\sum_{i=1}^{n} = C_{i}P_{i-1}I_{i} + C_{i}Q_{i-1}$$
 (1)

$$A_{i}T_{i} - C_{i}P_{i-1}T_{i} = B_{i}T_{i+1} + D_{i} + C_{i}Q_{i-1}$$





CFD-NHT-EHT



The above equations are recursive -i.e., **In order to get** P_i , Q_i , P_1 and Q_1 must be known. **In order to get** P_1 , Q_1 , use Eq.(a)

$$A_i T_i = B_i T_{i+1} + C_i T_{i-1} + D_i, i = 1, 2, \dots, M1$$
 (a)

End condition: $i=1, C_i=0; i=M1, B_i=0$

Applying Eq.(a) to i=1, and comparing it with Eq. (b), the expressions of P_1 , Q_1 can be





D

obtained: $i = 1, C_1 = 0, A_1T_1 = B_1T_2 + D_1$

$$T_1 = \frac{B_1}{A_1}T_2 + \frac{D_1}{A_1} \longrightarrow P_1 = \frac{B_1}{A_1}; \quad Q_1 = \frac{D_1}{A_1}$$

(2) Back substitution(回代) — Starting from M1 via Eq.(b) to get T_i sequentially (顺序地)

$$T_{M1} = P_{M1}T_{M1+1} + Q_{M1}, \quad P_i = \frac{B_i}{A_i - C_i P_{i-1}};$$

End condition:
 $i = M1, B_i = 0$
 $T_{M1} = Q_{M1}T_{i-1} = P_{i-1}T_i + Q_{i-1}$ to get: $T_{M1-1}, \dots, T_2, T_1.$



CFD-NHT-EHT

3. Implementation of Thomas algorithm for 1st kind B.C.

For 1st kind B.C., the solution region is from i=2,....to M1-1=M2.

Applying Eq.(b) to i=1 with given $T_{1,given}$:

$$T_1 = P_1 T_2 + Q_1 \longrightarrow P_1 = 0; \quad Q_1 = T_{1,given}$$

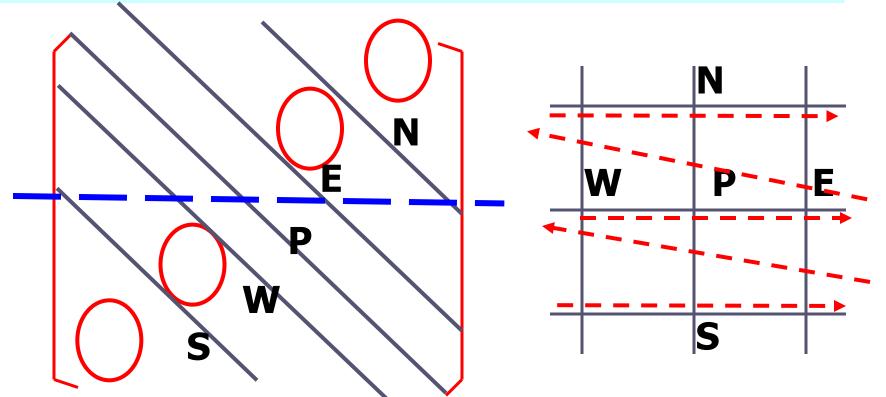
Because T_{M1} is known, back substitution should be started from M_2 : $T_{M2} = P_{M2}T_{M1} + Q_2$

When the ASTM is adopted to deal with B.C. of 2nd, and 3rd kind, the numerical B.C. for all cases is regarded as 1st kind, and the above treatment should be adopted. 10/56



4.4.2 ADI method for solving multi-dimensional problem

1. Introduction to the matrix of 2-D problem



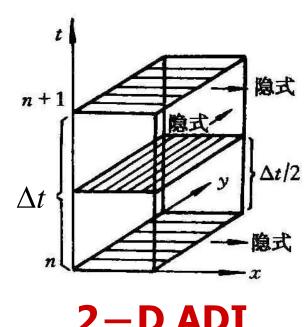
1-D storage (一维存储) of variables and its relation to matrix coefficients

Numerical methods for solving ABEqs. of 2-D problems.

(1) Penta-diagonal algorithm(PDMA, 五对角阵算法)

(2) Alternative(交替的)-direction Implicit (ADI, 交替方向隐式方法)

2. 3-D Peaceman-Rachford ADI method



Dividing Δt into three uniform parts In the 1st $\Delta t / 3$ implicit in x direction, and explicit in y, z directions; In the 2nd and 3rd $\Delta t / 3$ implicit in y, z direction, respectively. 西安交通大學

Set $u_{i,j,k}$, $v_{i,j,k}$ the temporary(临时的) solutions at two sub-time levels

$\delta_x^2 T_{i,j,k}^n$ -CD for 2nd derivative at n time level in x direction

1st subtime level $\frac{u_{i,j,k} - T_{i,j,k}^n}{\Delta t/3} = a(\delta_x^2 u_{i,j,k} + \delta_y^2 T_{i,j,k}^n + \delta_z^2 T_{i,j,k}^n)$

2nd subtime level: $\frac{v_{i,j,k} - u_{i,j,k}^n}{\Delta t / 3} = a(\delta_x^2 u_{i,j,k} + \delta_y^2 v_{i,j,k} + \delta_z^2 u_{i,j,k})$

 $\frac{\mathbf{3^{rd} sub-}}{\mathbf{time level}} \quad \frac{T_{i,j,k}^{n+1} - v_{i,j,k}^{n}}{\Delta t / 3} = a(\delta_x^2 v_{i,j,k} + \delta_y^2 v_{i,j,k}^{n} + \delta_z^2 T_{i,j,k}^{n+1})$



Stability condition by von Neumann method:

$$a\Delta t(\frac{1}{\Delta x^2} + \frac{1}{\Delta y^2} + \frac{1}{\Delta z^2}) \le 1.5$$

Is the allowed maximum time step three times of 1-D case?

Actually, No!

For 2-D case P-R method is absolutely stable.

3. Two "ADI" methods: ADI-implicit(交替方向隐式) for transient problems and ADI-iteration(交替方向迭代) multi-dimensional problems. They are very similar.



5 FDHT in Circular Tubes

4.5.1 Introduction to FDHT in tubes and ducts

- 4.5.2 Physical and Mathematical Models
- 4.5.3 Governing equations and their nondimensional forms
- **4.5.4 Conditions for unique solution**
- 4.5.5 Numerical solution method
- 4.5.6 Treatment of numerical results

4.5.7 Discussion on numerical results



4.5 Fully Developed HT in Circular Tubes

4.5.1 Introduction to FDHT in tubes and ducts

1. Simple fully developed heat transfer

Physically: Velocity components normal to flow direction equal zero; Fluid dimensionless temperature distribution is independent on(无关) the position in the flow direction

Mathematically: Both dimensionless momentum and energy equations are of **diffusion type**.

Present chapter is limited to simple cases.

(1) あ安文道大学

FDHT in straight duct is an example of simple cases. $\frac{\partial}{\partial x} \left(\frac{T_{w,m} - T}{T_{w,m} - T_{h}} \right) = 0$

2. Complicated FDHT

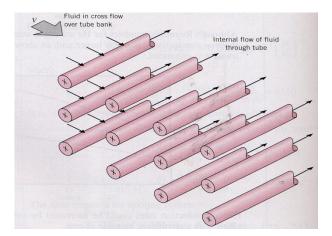
In the cross section normal to flow direction there exist velocity components, and the dimensionless temperature depends on the axial position, often exhibits periodic (周期的) character. The full Navier-Stokes equations must be solved。

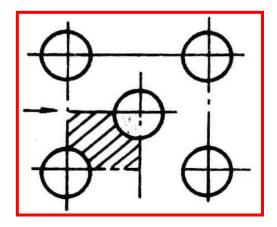
This subject is discussed in Chapter 11 of the textbook.



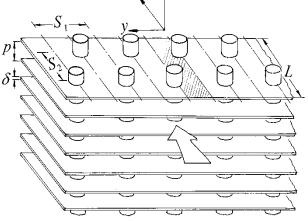


Examples of complicated FDHT

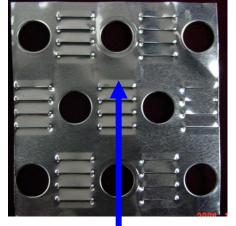


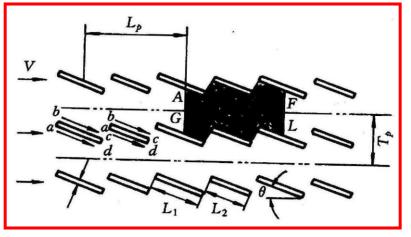


Tube bundle (bank) (管束)









Louver fin (百叶窗翅片)

18/56

1) 西安交通大學

3. Collection of partial examples

Table 4-5 Numerical examples of simple FDHT

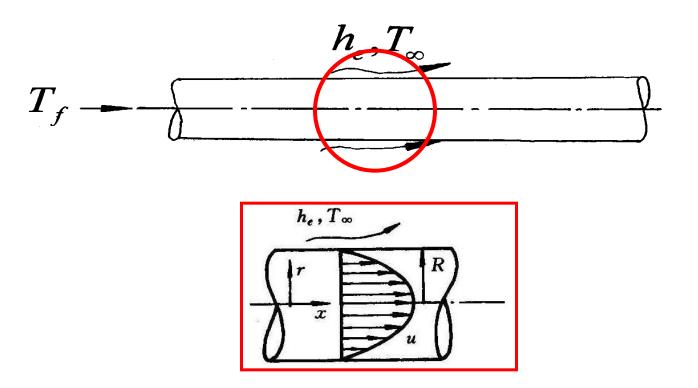
No	Cross section	B. Condition	Refs
1.	\bigcirc	均匀壁温;给定周向 热流分布;轴向热流 呈指数变化;外部对 流换热	[23,24, 25,26,27]
2		均匀壁温;均匀热流 及其组合	. 转引自[23]
3		均匀壁温;周向任意 分布热流;轴向均匀 热流;一组对边均匀 壁温,另一线绝热	[28,29,30]

See pp. 106-109 for details



4.5.2 Physical and mathematical models

A laminar flow in a long tube is cooled (heated) by an external fluid with temp. T_{∞} and heat transfer coefficient h_e . Determine the heat transfer coefficient and Nusselt number in the FDHT region.





1.Simplification (简化) assumptions

- (1) Thermo-physical properties are constant;
- (2) Axial heat conduction in the fluid is neglected
- (3) Viscous dissipation (耗散)is neglected;
- (4) Natural convection is neglected;
- (5) Wall thermal resistance is neglected;
- (6) The flow is fully developed:

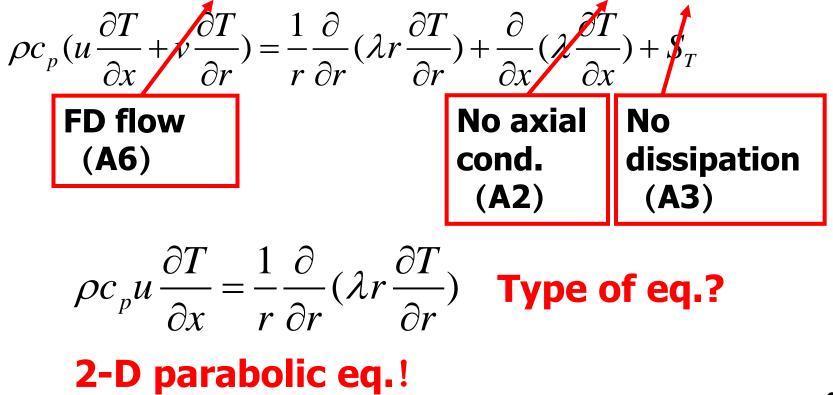
$$\frac{u}{u_m} = 2[1 - (\frac{r}{R})^2]; \quad v = 0$$



2. Mathematical formulation (描述)

(1) Energy equation

Cylindrical coordinate, symmetric temp. distribution, and no natural convection (A4):





CFD-NHT-EHT

(2) Boundary condition

$$r = 0, \frac{\partial T}{\partial r} = 0$$
 (Symmetric condition);

 $n_{e}(1 - I_{\infty})$

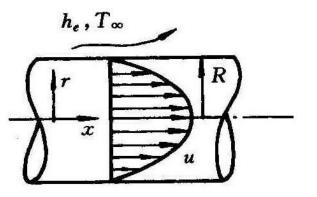
Internal fluid thermal conductivity

 $r = \kappa$,

External (外部)convective heat transfer

No wall thermal resistance(A5), tube outer radius = R; .

 ∂r



condition!)



4.5.3 Governing eqs. and dimensionless forms

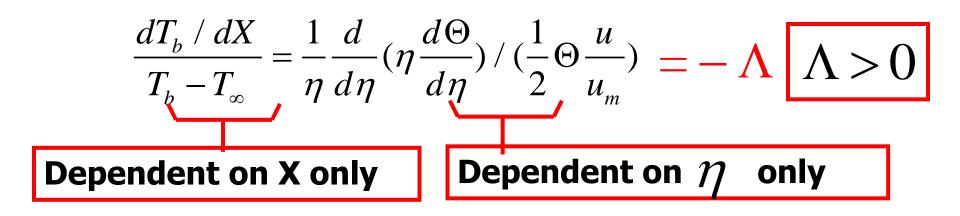
From FD condition a dimensionless temp. can be introduced, transforming the PDE to ordinary eq..

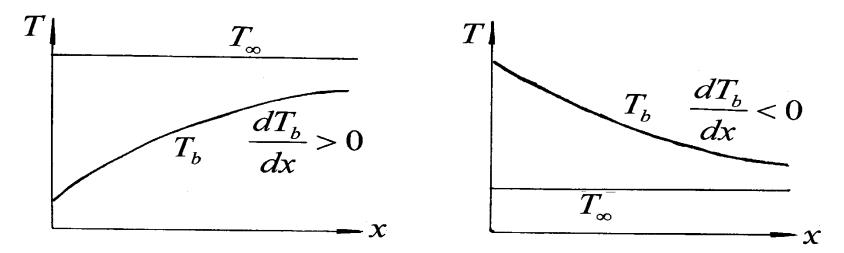
Defining
$$\Theta = \frac{T - T_{\infty}}{T_b - T_{\infty}}$$
 $\qquad \frac{T - T}{T_b - T}$ $\qquad \frac{T - T}{T - T}$
Then: $T = \Theta(T_b - T_{\infty}) + T_{\infty}$; $\frac{\partial T}{\partial x} = \Theta \frac{\partial T_b}{\partial x} = \Theta \frac{dT_b}{dx}$
Defining dimensionless space and "time" coordinates:
 $\eta = \frac{r}{R}$; $X = \frac{x}{R \bullet Pe}$ $Pe = \frac{2R\rho c_p u_m}{\lambda} = \frac{2Ru_m}{a}$
Constant properties (A 1)



CFD-NHT-EHT

Energy eq. can be rewritten as:





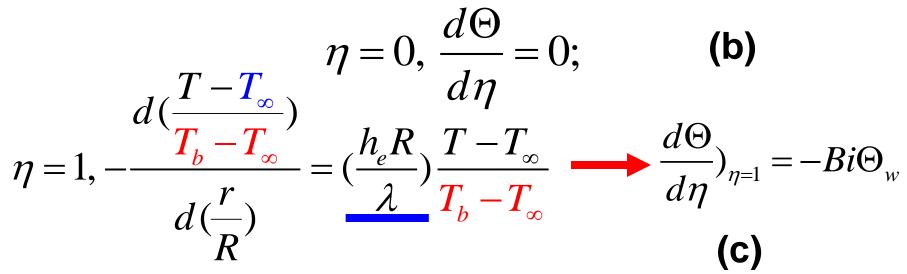
 Λ is called **eigenvalue** (特征值)



Following ordinary PDE for the dimensionless temperature. eq. can be obtained

$$\frac{1}{\eta} \frac{d}{d\eta} \left(\eta \frac{d\Theta}{d\eta} \right) / \left(\frac{1}{2} \Theta \frac{u}{u_m} \right) = -\Lambda$$
 (a)

The original two B.Cs. are transformed (转换成) into:



Question: whether from Eqs.(a)-(c) a unique (唯一的) solution can be obtained?

4.5.4 Analysis of condition for unique solution Because of the homogeneous (齐次性) character : Every term in the differential equation contains a linear part of dependent variable or its 1st/2nd derivative.

$$\frac{1}{\eta} \frac{d}{d\eta} (\eta \frac{d\Theta}{d\eta}) / (\frac{1}{2} \Theta \frac{u}{u_m}) = -\Lambda \longrightarrow \frac{1}{\eta} \frac{d}{d\eta} (\eta \frac{d\Theta}{d\eta}) = -\Lambda (\frac{1}{2} \Theta \frac{u}{u_m})$$

In addition, the given B.Cs. are also homogeneous:

$$\eta = 0, \ \frac{d\Theta}{d\eta} = 0; \qquad \qquad \frac{d\Theta}{d\eta})_{\eta=1} = -Bi\Theta_w$$

For the above mathematical formulation there exists an uncertainty (不确定性) of being able to be multiplied by a constant for its solution.



While in order to solve the problem, the value of Λ in the formulation has to be determined.

In order to get a unique solution and to specify the eigenvalue, we need to supply one more condition!

We examine the definition of dimenionless temperature:

$$\Theta_{\mathbf{b}} = \left(\frac{T - T_{\infty}}{T_b - T_{\infty}}\right)_{\mathbf{b}} = \frac{T_b - T_{\infty}}{T_b - T_{\infty}} \equiv \mathbf{1.0}$$

Physically, the averaged temp. is defined by

$$\Theta_b = \frac{\int_0^R 2\pi r u \Theta dr}{\pi R^2 u_m} = 2 \int_0^1 \frac{r}{R} \frac{u}{u_m} \Theta d\left(\frac{r}{R}\right) = \mathbf{1}$$

(2) 百步交通大學

CFD-NHT-EHT

Thus the complete formulation is:

$$\frac{1}{\eta} \frac{d}{d\eta} (\eta \frac{d\Theta}{d\eta}) + \Lambda(\frac{1}{2} \Theta \frac{u}{u_m}) = 0 \quad (a)$$

$$\eta = 0, \frac{d\Theta}{d\eta} = 0; \quad (b)$$

$$\frac{d\Theta}{d\eta})_{\eta=1} = -Bi\Theta_w \quad (c)$$

$$\int_0^1 \eta \frac{u}{u_m} \Theta d\eta = 1/2 \quad (d)$$
Non-homogeneous term!





4.5.5 Numerical solution method

$$\frac{1}{\eta}\frac{d}{d\eta}(\eta\frac{d\Theta}{d\eta}) + \Lambda(\frac{1}{2}\Theta\frac{u}{u_m}) = 0$$

This is a 1-D conduction equation with a source term! $\frac{\Lambda}{2} \ominus \frac{u}{u_m}$, whose value should be determined during the solution process iteratively.

Patankar – Sparrow proposed following numerical solution method:

(1) Let
$$\Theta = \Lambda \phi$$

Because of the homogeneous character, the form of the equation is not changed only replacing Θ by ϕ .

(1) 百安交通大學

$$\frac{1}{\eta} \frac{d}{d\eta} (\eta \frac{d\phi}{d\eta}) + \Lambda(\frac{1}{2}\phi \frac{u}{u_m}) = 0 \qquad (a)$$

$$\eta = 0, \ \frac{d\phi}{d\eta} = 0; \qquad (b)$$

$$\frac{d\phi}{d\eta}_{\eta=1} = -Bi\phi_w \qquad (c)$$

$$\int_0^1 \eta \frac{u}{u_m} \Lambda \phi d\eta = 1/2 \qquad (d) \longrightarrow$$

Non-homogeneous term

 $\Lambda = 1/(2\int_0^1 \eta \frac{u}{u_m} \phi d\eta)$ It can be used to iteratively determine the eigenvalue.

CFD-NHT-EHT





- (2) Assuming an initial field ϕ^* , get Λ^*
- (3) Solving an ordinary differential eq. with a source term to get an improved ϕ
- (4) Repeating the above procedure until:

$$\left|\frac{\phi^* - \phi}{\phi}\right| \le \varepsilon, \quad \varepsilon = 10^{-3} \sim 10^{-6}$$

This iterative procedure is easy to approach convergence:

$$S = \Lambda \frac{1}{2} \frac{u}{u_m} \phi = \frac{(u/u_m)\phi}{4 \int_0^1 \eta (u/u_m)\phi d\eta} = \frac{(1-\eta^2)\phi}{4 \int_0^1 \eta (1-\eta^2)\phi d\eta}$$

$$\Lambda = 1/(2 \int_0^1 \eta \frac{u}{u_m} \phi d\eta)$$

32/56



 ϕ exists in both numerator and denominator, thus only the distribution, rather than absolute value will affect the source term.

4.5.6 Treatment of numerical results

Two ways for obtaining heat transfer coefficient:

1. From solved temp. distribution using Fourier's law of heat conduction and Newton's law of cooling:

$$r = R, -\lambda \frac{\partial T}{\partial r} = h(T_w - T_b) \longrightarrow h = -\lambda \frac{\partial T}{\partial r}_{r=R} \frac{1}{T_w - T_b}$$

For inner fluid

Different from Boundary condition

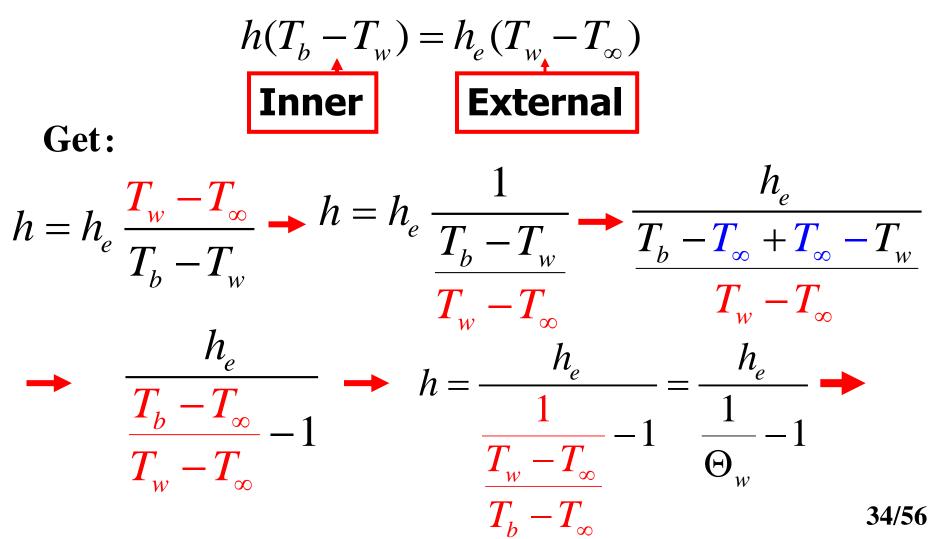
$$r = R, -\lambda \frac{\partial T}{\partial r} = h_e (T - T_\infty)$$
 33/56

3 历安交通大学

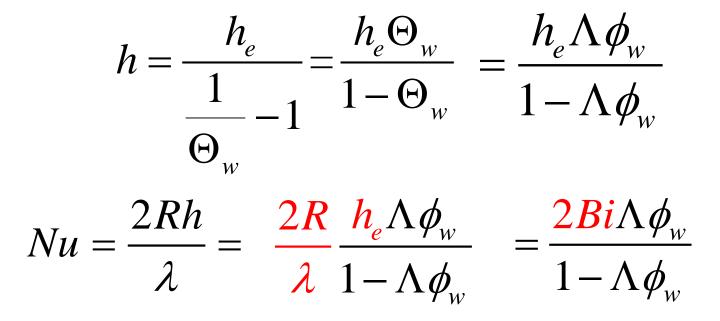


2. From the eigenvalue (特征值):

From heat balance between inner and external heat transfer







From the specified values Bi, the corresponding eigenvalues, Λ , can be obtained. Thus it is not necessary to find the 1st derivative at the wall of function ϕ for determining Nusselt number.

4.5.7 Discussion on numerical results



Table 4-6 Numerical results of FDHT in tubes

Bi	Λ	Nu
0	0	4.364 (Nu)
0.1	0.381 8	4.330
0.25	0.894 3	4.284
0.5	1.615	4.221
1	2.690	4.122
2	3.995	3.997
5	5.547	3.840
10	6.326	3.758
100	7.195	3.663
00	7.314	<u>3.657</u> (<i>Nu</i>)



No!

1. *Bi* effect: **From definition** $Bi = \frac{Rh_e}{Rh_e}$ $Bi \rightarrow \infty$, $h_{a} \rightarrow \infty$ External heat transfer is very strong, the wall temp. approaches fluid temp. This is corresponding to constant wall temp condition, Thus **Nu=3.66**

Is this adiabatic? $Bi \rightarrow 0, h_{a} \rightarrow 0$ Т ΔT Very large constant. $h_{\rm o}$ Very small T_{∞}

Product of very small HT coefficient and very large temp. difference makes heat flux almost

 $q = h_{o}\Delta T \approx const$ 37/56

西安交通大學

2. Computer implementation of $Bi \rightarrow \infty$ and Bi = 0

Bi $\rightarrow \infty$ by progressively (逐渐地) increasing Bi:

 $Bi = 10^5, 10^6, 10^7....$

Bi=0 by progressively decreasing **Bi**:

Bi= 0.1, 0.01, 0.001, 0.0001, 0.00001, Double decision (双精度)must be used for Computation:

$$Nu = \frac{2Bi\Lambda\phi_{w}}{1-\Lambda\phi_{w}}, Bi \to 0, \Lambda \to 0, \Lambda\phi_{w} \to 1 \longrightarrow \frac{0}{0}$$
38/56



4.6 Fully Developed HT in Rectangle Ducts

4.6.1 Physical and mathematical models

4.6.2 Governing eqs. and their dimensionless forms

4.6.3 Condition for unique solution

4.6.4 Treatment of numerical results

4.6.5 Other cases(20171011)



Brief review of 2017-10-11 lecture key points

1. TDMA solution algorithm for 1-D problem

(1) Elimination (消元)—Reducing the unknowns at each line from 3 to 2

$$A_{i}T_{i} = B_{i}T_{i+1} + C_{i}T_{i-1} + D_{i}(a) \longrightarrow T_{i-1} = P_{i-1}T_{i} + Q_{i-1} (b)$$

$$P_{i} = \frac{B_{i}}{A_{i} - C_{i}P_{i-1}}; Q_{i} = \frac{D_{i} + C_{i}Q_{i-1}}{A_{i} - C_{i}P_{i-1}}; P_{1} = \frac{B_{1}}{A_{1}}; Q_{1} = \frac{D_{1}}{A_{1}}$$

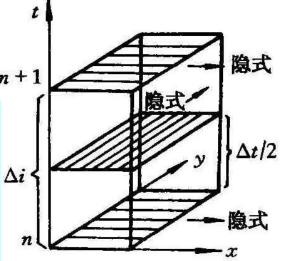
(2) Back substitution(回代)—Starting from the last node via Eq.(b) to get T_i sequentially

2. ADI method for solving 2-D unsteady problem Dividing Δt into two uniform parts; In the 1st $\Delta t / \frac{2}{4}$



implicit in x direction, and explicit in y direction; In the 2nd $\Delta t / 2$ implicit in y direction, and explicit in x direction.

By implementing two times of TDMA the algebraic equations for forwarding one time step is solved.



3. Homogeneous problems

Every term in the differential equation and boundary conditions only contains a linear part of dependent variable or its 1st or 2nd derivative.

For such a mathematical formulation there exists an uncertainty of being able to be multiplied by a constant for its solution.



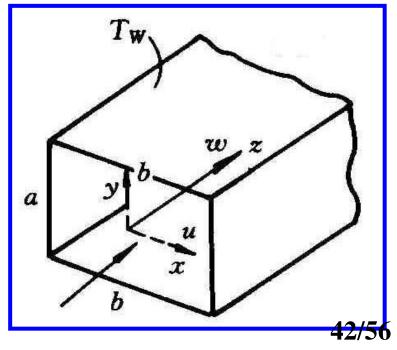
4.6 Fully Developed HT in Rectangle Ducts

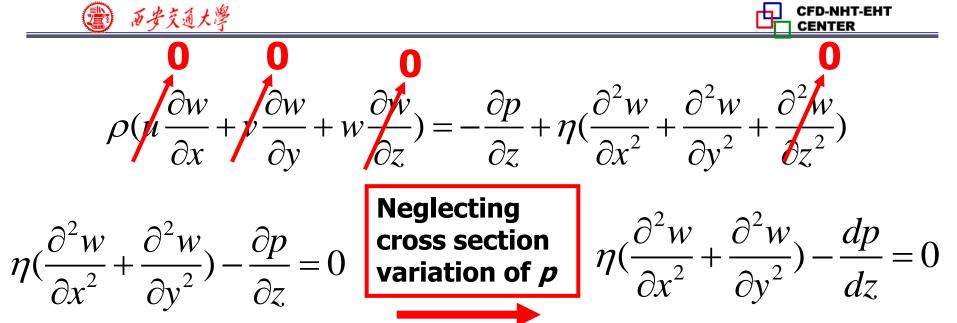
4.6.1 Physical and mathematical models

Fluid with constant properties flows in a long rectangle duct with a constant wall temp. Determine the friction factor and HT coefficient in the fully developed region for laminar flow.

1. Momentum eq.

For the fully developed flow *u*=*v*=0, only the velocity component in z-direction is not zero. Its governing equation:



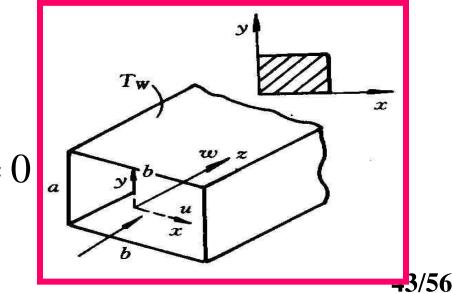


Taking ¹/₄ region as the computational domain because of symmetry. Boundary conditions are:

 $\frac{\partial w}{\partial n} =$

- At the wall, w=0;
- At center line,

First order normal derivative equals zero:







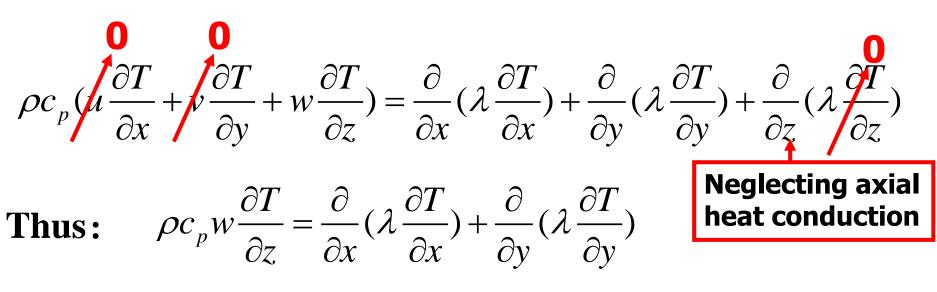
Defining a dimensionless velocity as :

$$W = \frac{\eta w}{-D^2 \frac{dp}{dz}}$$

where D is the referenced length, say: D = a, or D = b. Defining dimensionless coordinates: X = x/D, Y = y/D, then: $\int \frac{\partial^2 W}{\partial X^2} + \frac{\partial^2 W}{\partial Y^2} + 1 = 0$ $\eta(\frac{\partial^2 w}{\partial x^2} + \frac{\partial^2 w}{\partial y^2}) - \frac{dp}{dz} = 0 \longrightarrow \begin{cases} \partial X & \forall A \\ At \text{ wall, } W=0; \\ At \text{ center lines, } \frac{\partial W}{\partial n} = 0 \end{cases}$ problem with a source term and a constant diffusivity η !

西安交通大學

2. Energy equation



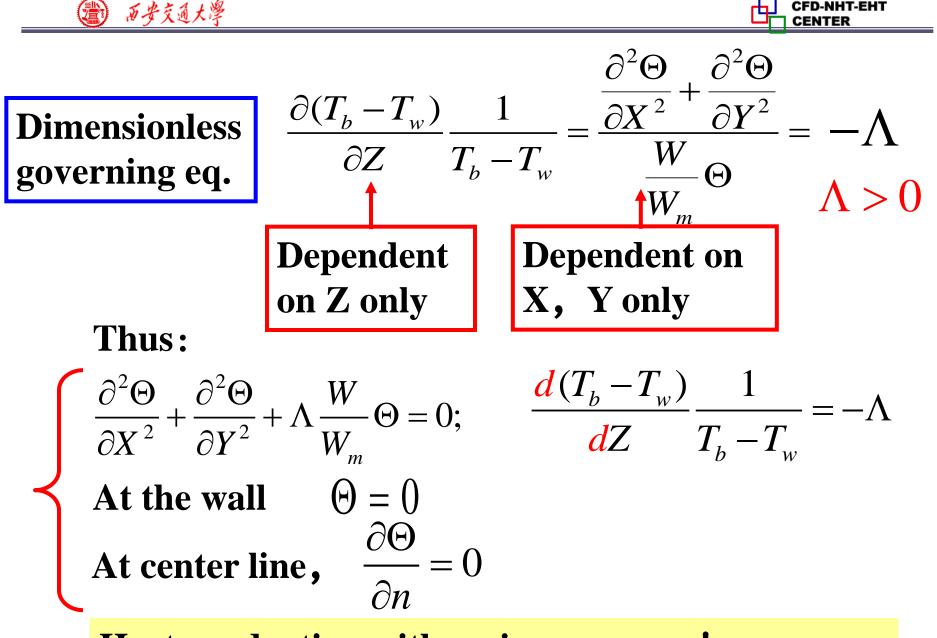
Type of equation? Parabolic ! Z is a one-way coordinate like time!

Boundary conditions: At the wall, $T=T_w$; At the center line, $\frac{\partial T}{\partial n} = 0$



4.6.2 Dimensionless governing equation

We should define an appropriate dimensionless temperature such that the dimension of the problem can be reduced from 3 to 2: **Separating the one-way coordinate** *z* **from the two-way coordinates** *x,y* •

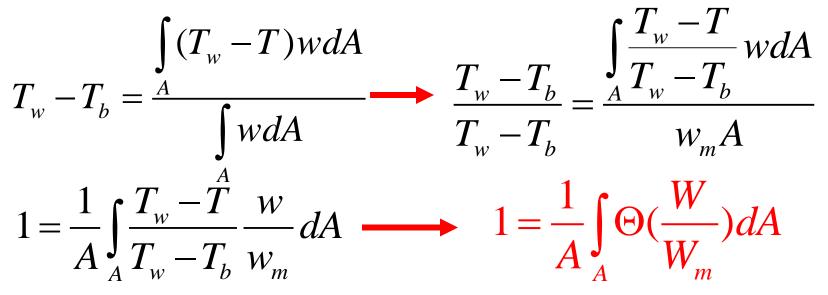


Heat conduction with an inner source!



4.6.3 Analysis on the unique solution condition

Because of the homogeneous character, these also exists an uncertainty of being magnifying by any times! Introducing average temperature (difference):



It is the additional condition for the unique solution.

Numerical solution method is the same as that for a circular tube.



4.6.4 Treatment of numerical results*

After receiving converged velocity and temperature fields, friction factor and Nusselt number can be obtained as follows:

1. fRe-for laminar problems fRe =constant: $f \operatorname{Re} = \left[-\frac{D_e \frac{dp}{dz}}{\frac{1}{2}\rho w_m^2}\right] \left(\frac{w_m D_e}{v}\right) \xrightarrow{\text{Definition of W}} W = \frac{\eta w}{-D^2 \frac{dp}{dz}} \quad f \operatorname{Re} = \frac{2}{W_m} \left(\frac{D_e}{D}\right)^2$

2. Nu – Making an energy balance : $\rho c_p w_m A \frac{dT_b}{dz} = qP$, *P* is the duct circumference length 49/56 (量) 而安交通大學

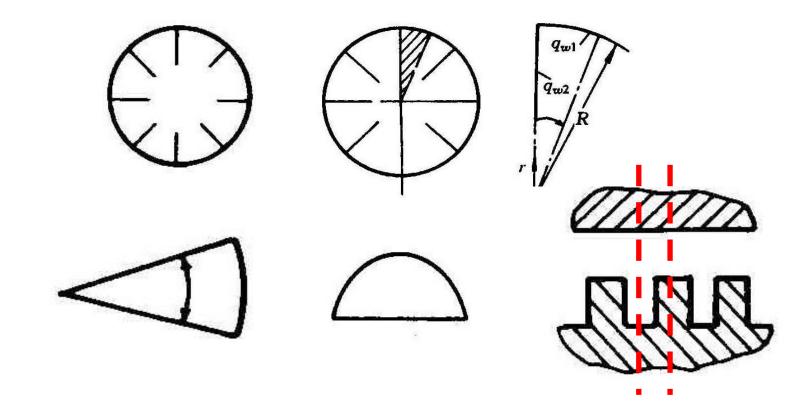
 $\frac{d(T_b - T_w)}{dZ} \frac{1}{T_b - T_w} = -\Lambda \quad \text{i.e., } \frac{dT_b}{dZ} = \frac{dT_b}{dz} DPe = (T_w - T_b)\Lambda$ $\frac{dT_b}{dZ} = \frac{1}{DPe} (T_w - T_b)\Lambda \quad \text{Substituting in}$ $\rho c_p w_m A \frac{dT_b}{dz} = qP$ yields $q = \frac{A\rho c_p w_m}{P} \frac{dT_b}{dz} = \frac{A\rho c_p w_m}{P} \frac{1}{DPe} \Lambda(T_w - T_b)$ yields: $q = \frac{A}{P} \frac{\lambda}{D^2} \Lambda(T_w - T_b)$ $Pe = \frac{\rho c_p w_m D}{\lambda}$ $Nu = \frac{hD_e}{\lambda} = \frac{q}{T_w - T_b} \frac{D_e}{\lambda} = \frac{1}{T_w - T_b} \frac{D_e}{\lambda} \frac{A}{P} \frac{\lambda}{D^2} \frac{\Lambda}{D^2} \frac{\Lambda}{D_e} (T_w - T_b) = \frac{1}{4} (\frac{D_e}{D})^2 \Lambda$ $D_e = \frac{4A}{P}$ 50/56 50/56



CFD-NHT-EHT

$$f \operatorname{Re} = \frac{2}{W_m} \left(\frac{D_e}{D}\right)^2 \quad Nu = \frac{1}{4} \left(\frac{D_e}{D}\right)^2 \Lambda$$

4.6.5 Other cases







Home Work 3

 $4-2(T_1=150,T_f=25),$ 4-4, 4-12, 4-14,4-18

Due in October 23



Problem 4-2: As shown in Fig. 4-22, in 1-D steady heat conduction problem, known conditions are: T_1 =150, Lambda=5, S=150, T_f =25, h=15, the units in every term are consistent. Try to determine the values of T_2 , T_3 ; Prove that the solution meet the overall conservation requirement even though only three nodes are used.

Problem 4-4: A large plate with thickness of 0.1 m, uniform source $S=50 \times 10^3 \text{ W/m}^3$, $\lambda = 10 \text{ W} / (\text{m} \cdot \text{C})$; One of its wall is kept at 75 °C, while the other wall is cooled by a fluid with $T_f = 25^{\circ}\text{C}$ and heat transfer coefficient $h = 50 \text{ W/m}^2 \cdot \text{C}$

Adopt Practice B, divide the plate thickness into three uniform CVs, determine the inner node temperature. Take 2nd order accuracy for the inner node, adopt the additional source term method for the right boundary node.

Problem 4-12:

Write a program using TDMA algorithm, and use the following method to check its accuracy: set arbitrary values of the coefficients A_i , B_i and C_i (i = 1,10). But B_1 and C_{10} should not be zero. Then setting the reasonable values of temperature T_1 ,..., T_{10} , calculate the corresponding constants D_i . Apply your program for solving T_i by using the values of A_i , B_i , C_i and D_i , and compare the results with the given value.

Problem 4-14:

According to the problem discussed in section 4.6(The fully developed heat convection in a circular tube), try to analyze the following three dimensionless temperature definitions

of
$$\Theta = \frac{T - T_w}{T_b - T_w}$$
, $\Theta = \frac{T - T_\infty}{T_w - T_\infty}$ and $\Theta = \frac{T - T_w}{T_\infty - T_w}$, which one is acceptable for separation of

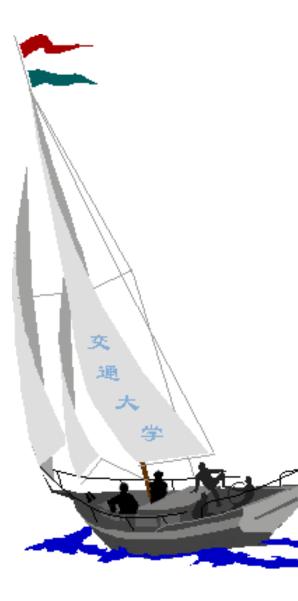
variables.»

Problem 4-18: Shown in Fig.4-25 is a laminar fully developed heat transfer in a duct of half circular cross. Try:

 Write the mathematical formulation of the heat transfer problem;
 Make the formulation dimensionless by introducing some dimensionless parameters;

(3) Derive the expressions for *fRe* and *Nu* from numerical solutions, where the characteristic length for *Re* and *Nu* is the equivalent diameter D_e .





同舟共济



People in the same boat help each other to cross to the other bank, where....