

Lattice Boltzmann for flow and transport phenomena

2. The lattice Boltzmann for porous flow and transport

Li Chen

XJTU, 2021/03/30

Mail: lichennht08@mail.xjtu.edu.cn

Webpage: <http://gr.xjtu.edu.cn/web/lichennht08>

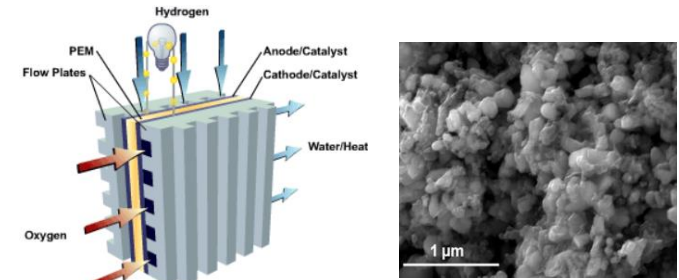
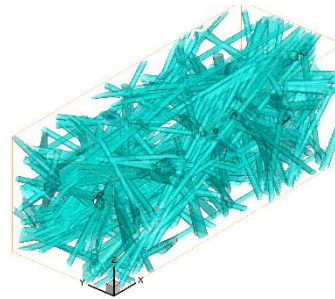
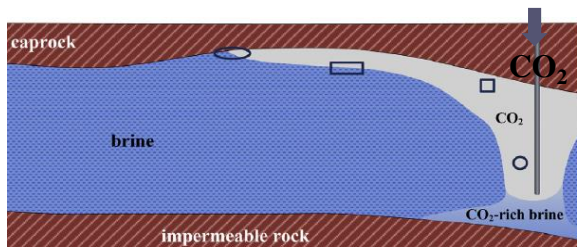
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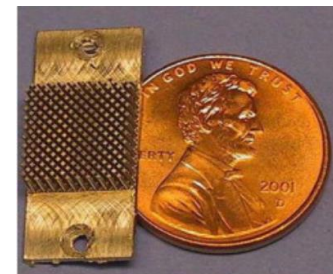
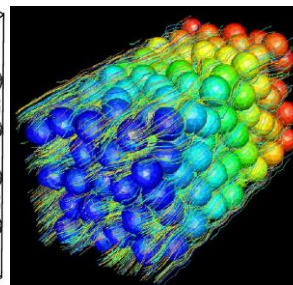
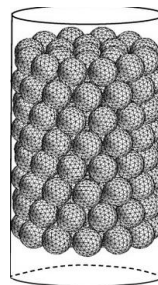
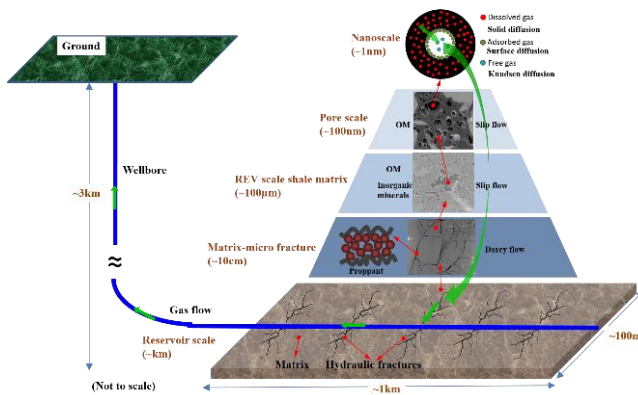
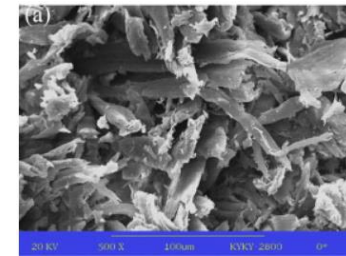
- **2.1 Background**
- **2.2 Structural characteristics of porous media**
- **2.3 Continuum-scale governing equation for porous media**
- **2.4 Pore-scale simulation: reconstruction of porous media**
- **2.5 Pore-scale simulation: LB for fluid flow**
- **2.6 Pore-scale simulation: LB for heat transfer**

2.1 Examples of porous media

- **Natural porous systems:** enhanced hydrocarbon and geothermal energy recovery, CO₂ geological sequestration,
- **Artificial porous systems:** fuel cell, reactor, catalysts, building material...



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传热传质





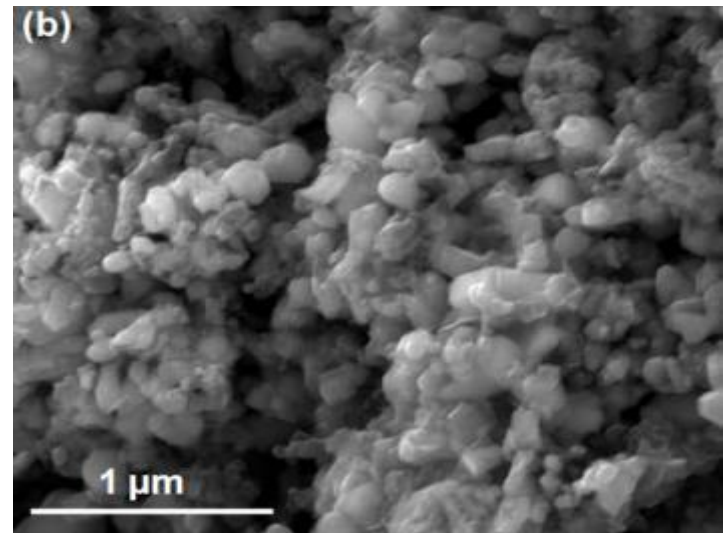
Stone



Carbon fiber



Metal foam



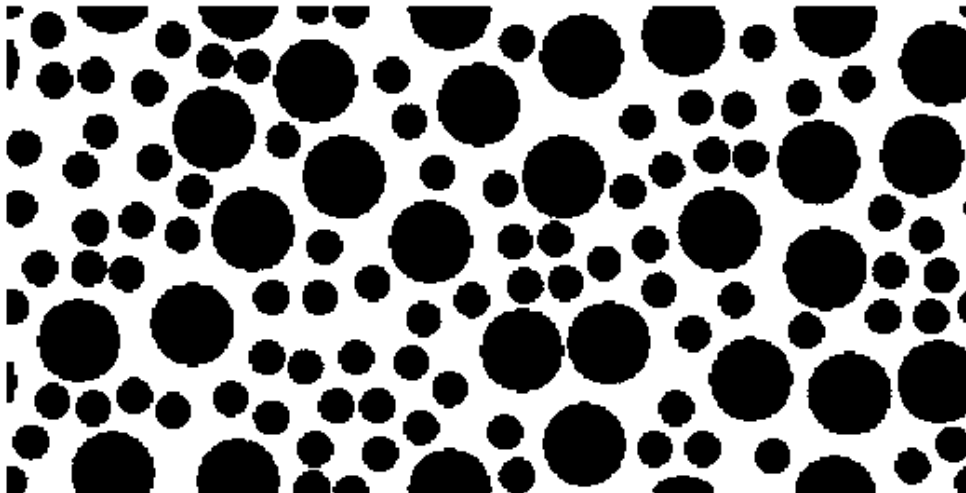
Catalyst

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- 2.1 Examples of porous media
- **2.2 Structural characteristics of porous media**
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2.2 Structural characteristics of porous media

- A material that contains plenty of pores (or voids) between solid skeleton through which fluid can transport.
- Two necessary elements: **skeleton** and **pores**; Skeleton: maintain the shape; Pores: provide pathway for fluid flow through



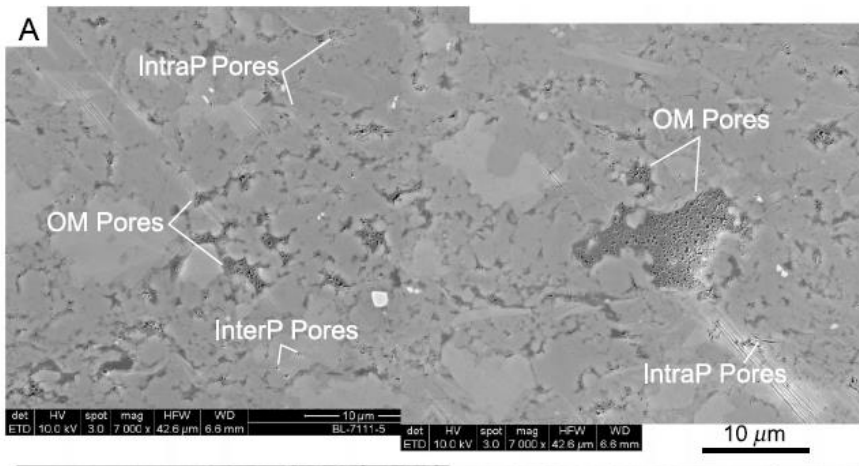
Black: solid
White: pores

2.2.1 Porosity

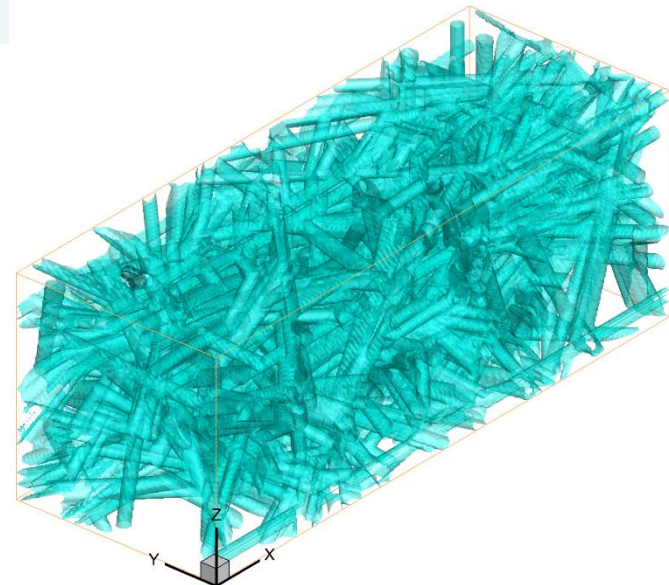
- The volume ratio between pore volume and total volume

$$\varepsilon = \frac{V_{\text{pore}}}{V_{\text{total}}}$$

- **Porosity maybe vary from near zero to almost unity.** Shale has low porosity, around 5%. Fiber-based porous media can have a porosity as high as 90%.



Shale: <10%



GDL: >70%

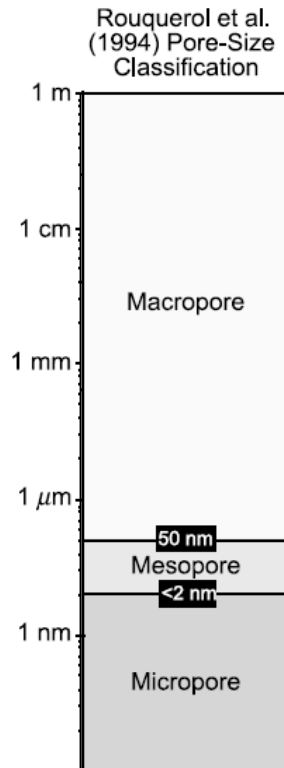
2.2.2 Pore size

Pore size terminology of IUPAC

International Union of Pure and Applied Chemistry

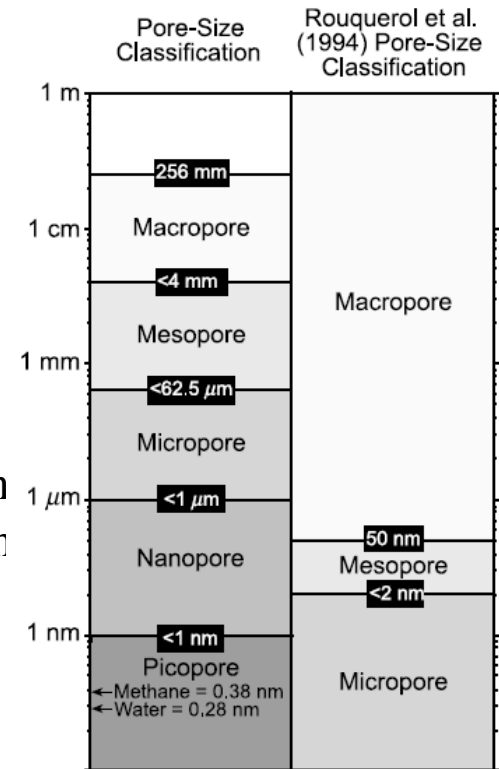
Rouquerol et al. (1994) Membrane

Micropores, <2nm
 Mesopores, 2~50nm
 Macropores, >50nm



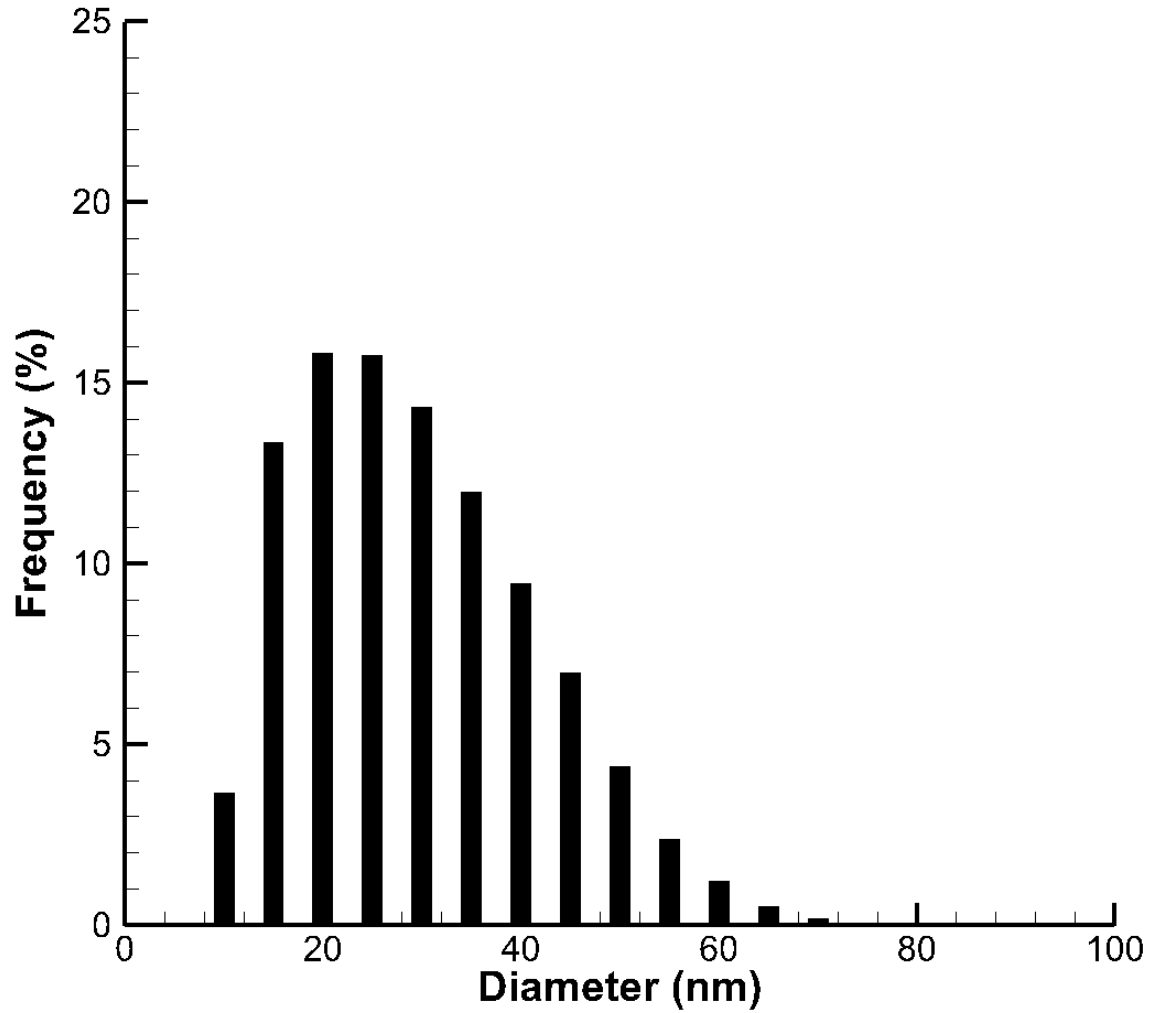
Choquette and Pray (1970) Carbonate rock

Micropores, <62.5 μm
 Mesopores, 62.5 μm~4mm
 Macropores, 4mm~256mm



Rouck et al. 2012, further added picopore and nanopore for study of shale.

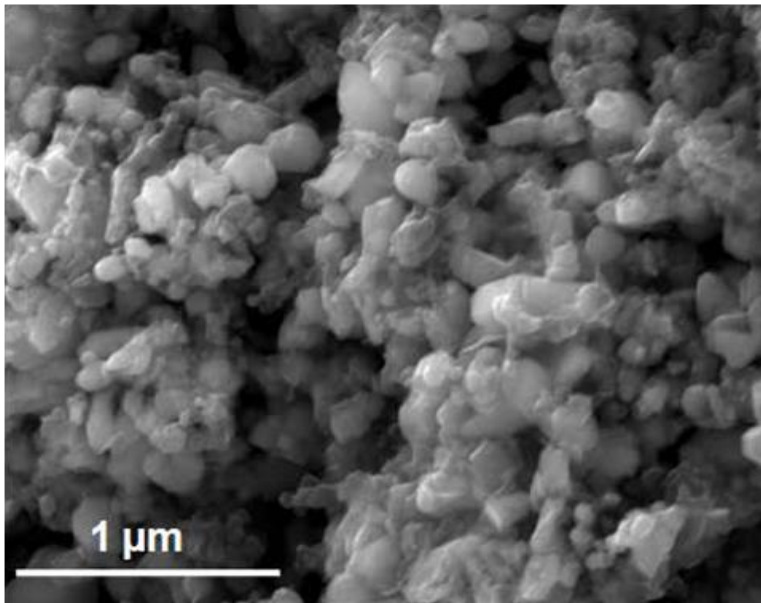
Pore size distribution



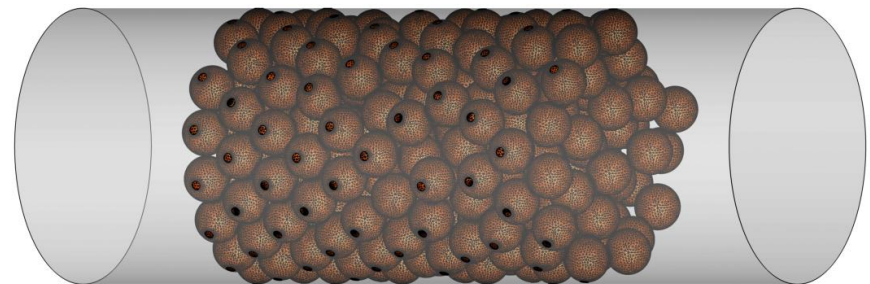
2.2.3 Specific surface area

Defined as the ratio between total surface area to the total volume.

An important parameter for porous media as one of the important type of porous media is catalyst, which requires high specific surface area for reaction.



Catalyst of Fuel cell

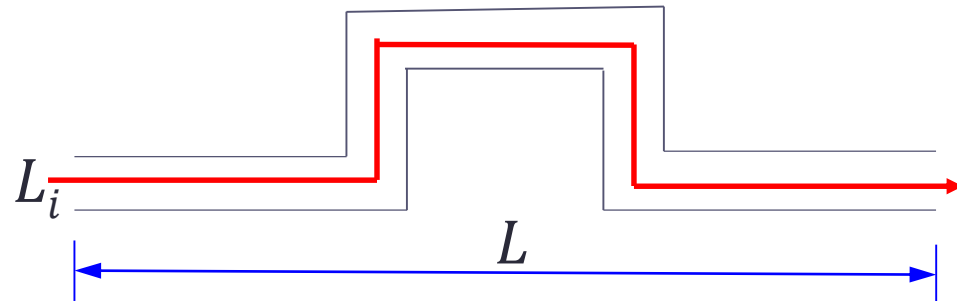


Packed-bed reactor

2.2.4 Tortuosity

Tortuosity: defined as the actual length traveled by a particle to the length of the media

$$\tau = \frac{L_i}{L}$$



Tortuosity is thus transport dependent, including flow, diffusion, heat transfer, electrical conduct, acoustic transport.

- For fluid flow it is “**hydraulic tortuosity**”
- For diffusion it is “**diffusivity tortuosity**”
- For electron transport, it is “**conductivity tortuosity**”

Except for some very simple porous structures, there is no clear consensus on the relation between these definitions.

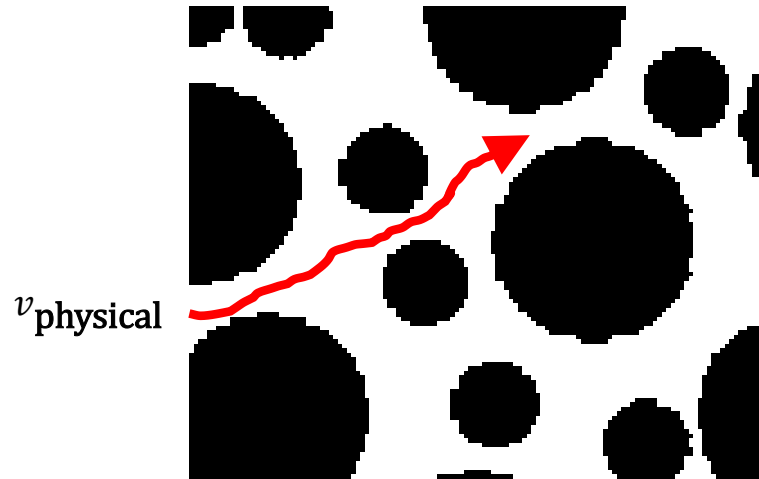
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Two velocity definition in a porous medium:

$$v_{\text{superficial}} = \epsilon v_{\text{physical}}$$

Porosity



V_{physical} : the actual flow velocity in the pores.

$V_{\text{superficial}}$ (表观速度): the averaged velocity in the entire domain.

$$V_{\text{superficial}} < V_{\text{physical}}$$

Fluent uses superficial velocity as the default velocity.

Continuum-scale equations for porous flow

$$\nabla \cdot \mathbf{u}_{\text{superficial}} = 0$$

$$\left(\frac{\mathbf{u}_{\text{superficial}}}{\varepsilon} \cdot \nabla \right) (\mathbf{u}_{\text{superficial}}) = -\frac{1}{\rho} \varepsilon \nabla(p) + \eta \nabla^2 (\mathbf{u}_{\text{superficial}}) + \mathbf{F}$$

$$\mathbf{F} = -\frac{\varepsilon \nu}{k} \mathbf{u} - \frac{\varepsilon F_\varepsilon}{\sqrt{k}} |\mathbf{u}| \mathbf{u}$$

$$\frac{\partial((\rho C_p)_{\text{eff}} T)}{\partial t} + (\mathbf{u}_{\text{superficial}} \cdot \nabla)(\rho C_p T) = \lambda_{\text{eff}} \nabla^2 T + S_{\text{eff}}$$

$$\lambda_{\text{eff}} = (1 - \varepsilon) \lambda_s + \varepsilon \lambda_f$$

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2.4 Reconstruction

The first step towards pore-scale modeling using the LBM is structure reconstruction.

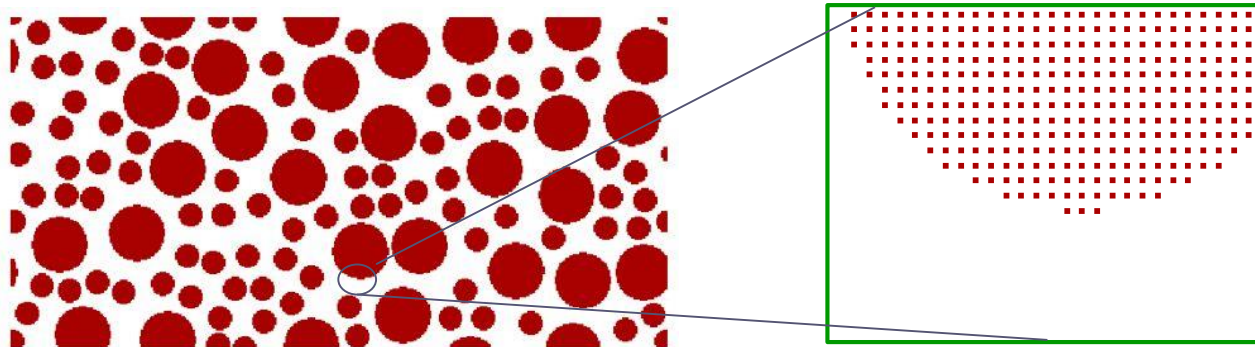
For a **nD** problem, where **D** is dimension, and **n** is 2 and 3 for two and three dimensional space, respectively, a **nD matrix is defined**

$$S=(n_x, n_y, n_z)$$

n_x , n_y and n_z is the mesh size of the domain in x , y and z direction.

In this matrix, $S_{i,j,k}=0$ represents fluid and 1 stands for solid. In such way the solid structure is defined and can be imported into the LB code.

Digitalized Structures



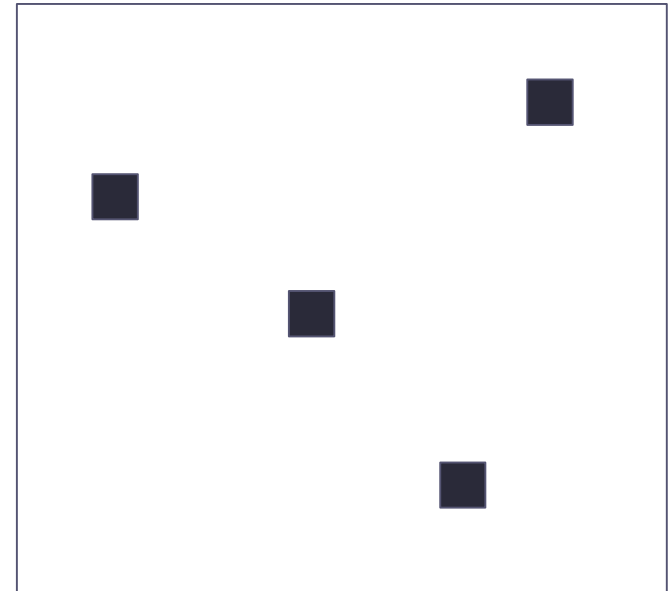
A 2D matrix is adopted to represent the porous media, with 1 as solid and 0 as fluid.

1 1 1 1 1 1 1 1 1	1 1 1 1 1 1 1 1 1	0 0 0 0 0 0 0 0 0
0 1 1 1 1 1 1 1 0	0 0 0 0 0 0 0 0 0	0 0 0 1 1 1 0 0 0
0 0 1 1 1 1 1 0 0	0 0 0 0 0 0 0 0 0	0 0 0 1 1 1 0 0 0
0 0 0 1 1 1 0 0 0	0 0 0 0 0 0 0 0 0	0 0 0 1 1 1 0 0 0
0 0 0 0 0 0 0 0 0	1 1 1 1 1 1 1 1 1	0 0 0 0 0 0 0 0 0

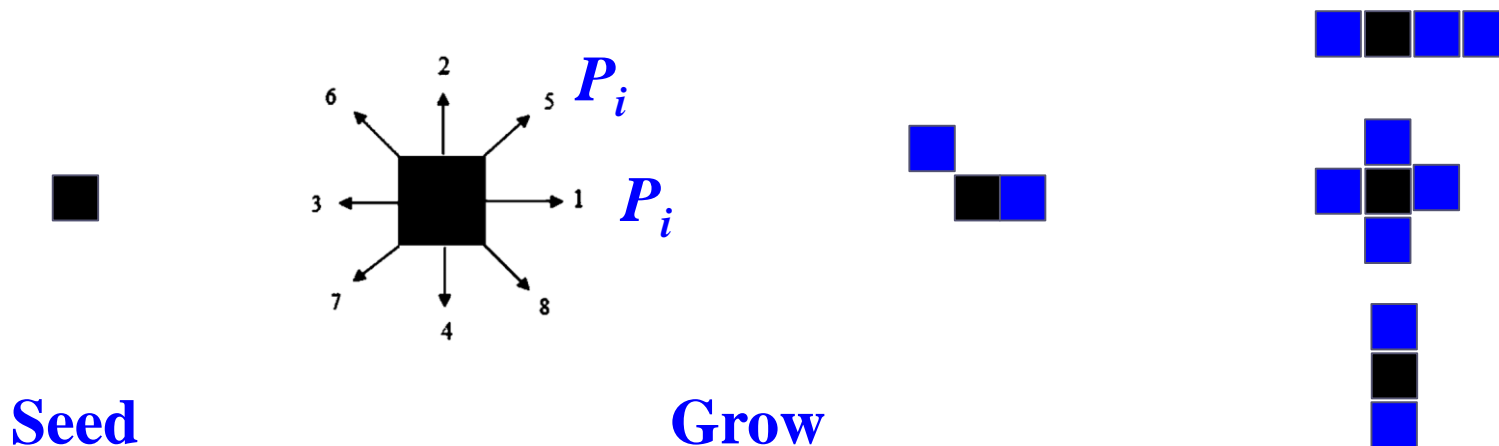
a. Quartet (四参数) structure generation set (QSGS) proposed by Wang et al. (2007)

Suppose a 2D domain with two constituents α and β (成分)

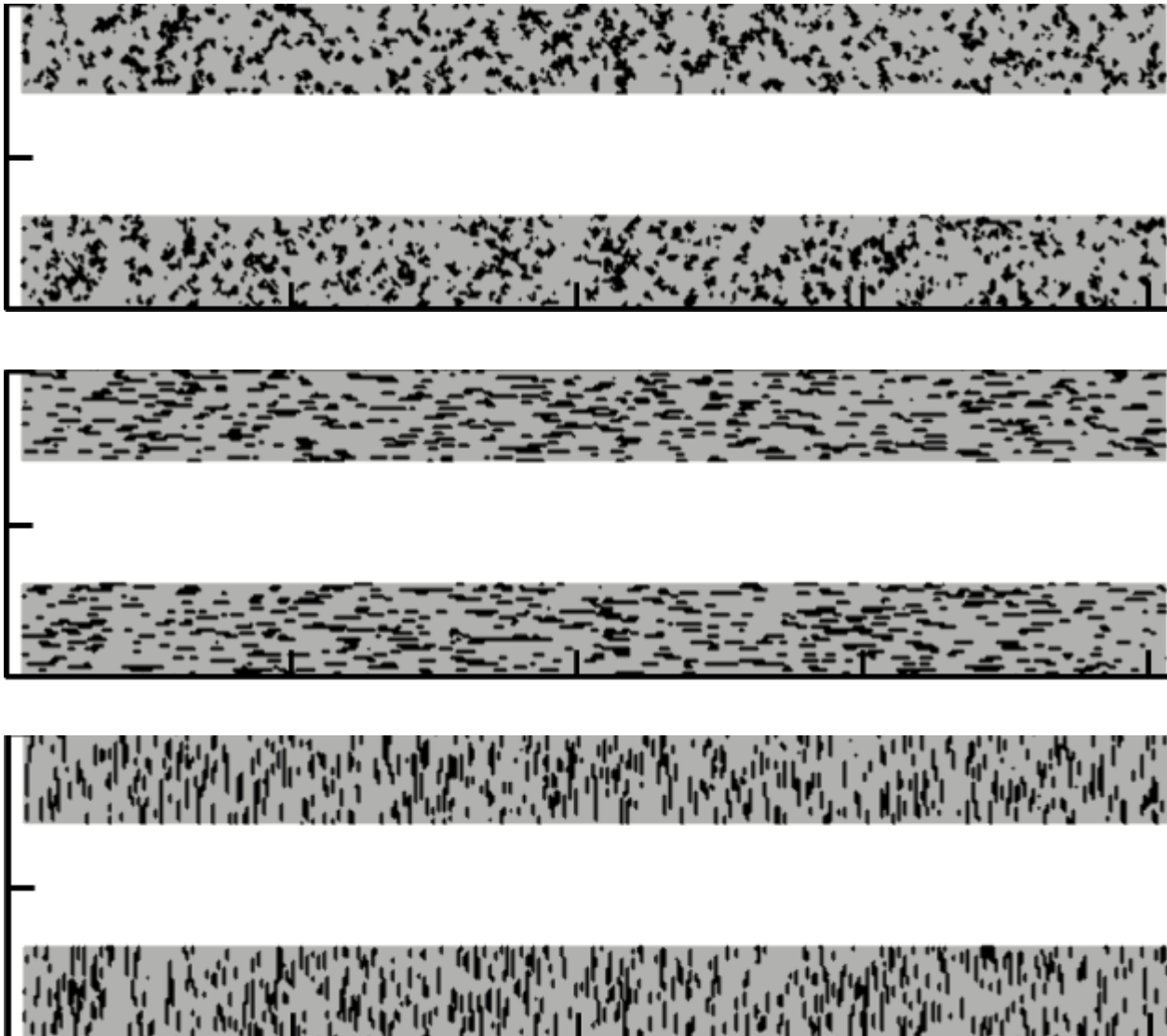
1. Randomly locate the cores of β in the domain based on a distribution probability, c_d , which is smaller than the volume fraction of β , ε_β . A random number within $(0,1)$ will be assigned to each node in the domain, and if the random number is no greater than c_d the node is selected as a core.



2. Grow an existing β node to its neighboring nodes based on another probability P_i with i representing the direction. In the present study only the nearest neighboring nodes are considered, namely four in the main direction (1,2,3,4) and the other four in the diagonal directions (5,6,7,8). For each direction, a new random number is generated, and if it is no greater than P_i the neighboring node in i direction becomes β .



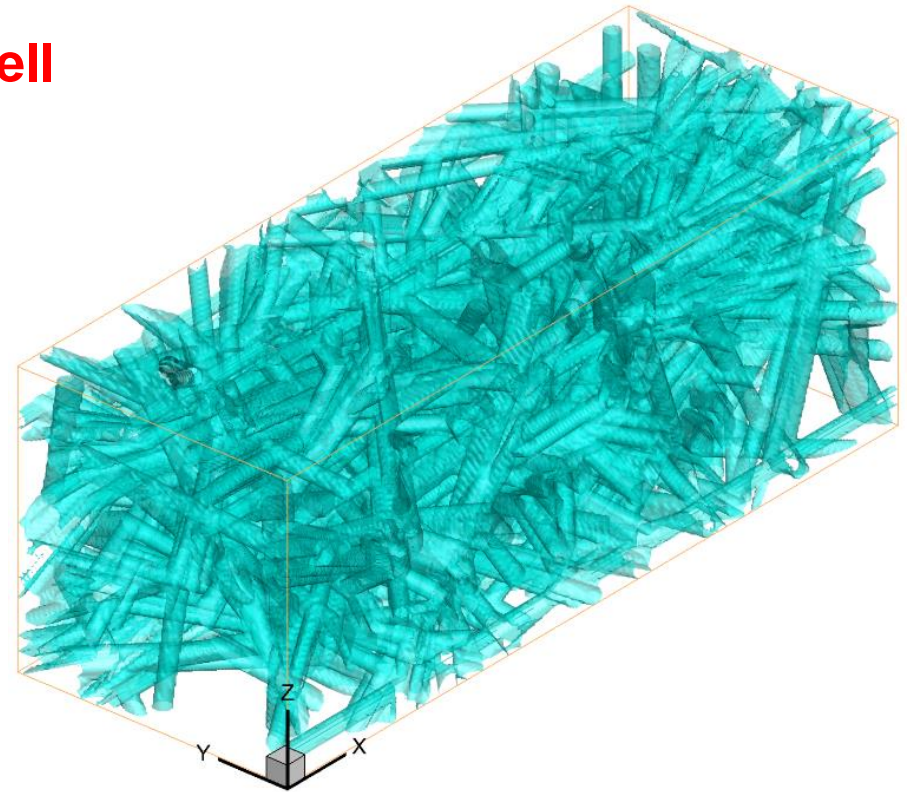
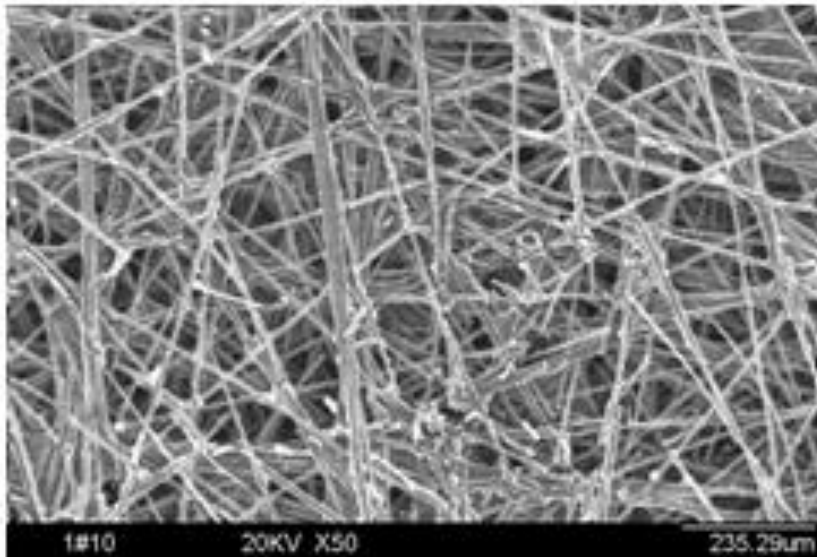
3. Repeating 1 and 2, until the volume fraction is obtained.



Schematic of the porous structures using QSGS

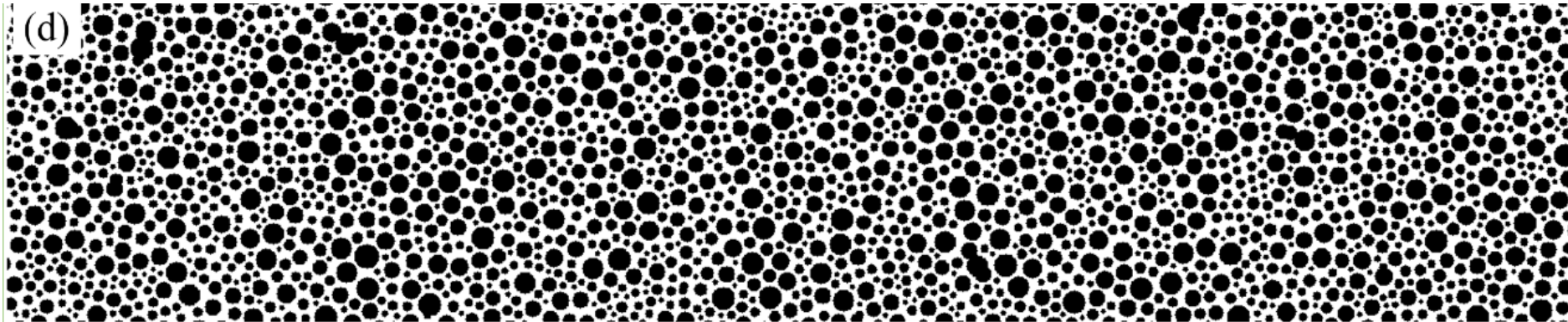
b. Reconstruction of fibrous porous media

Fiber porous media in PEM fuel cell



1. **L. Chen**, YL He, WQ Tao, P Zelenay, R Mukundan, Q Kang, Pore-scale study of multiphase reactive transport in fibrous electrodes of vanadium redox flow batteries, *Electrochimica Acta* 248, 425-439;
2. **L. Chen***, H.B. Luan, Y.-L. He, W.-Q. Tao, Pore-scale flow and mass transport in gas diffusion layer of proton exchange membrane fuel cell with interdigitated flow fields, 2012, 51, 132-144, *International journal of thermal science*

c. Random spheres with uniform gap



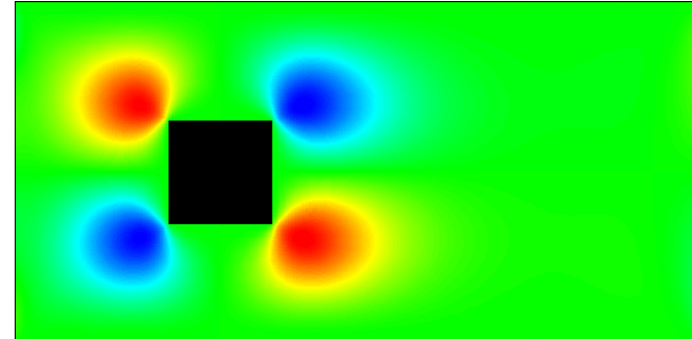
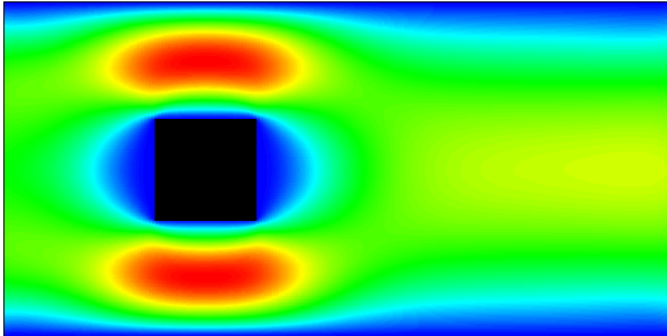
Li Chen, et al. Pore-scale study of effects of macroscopic pores and their distributions on reactive transport in hierarchical porous media, *Chemical Engineering Journal*, 2018,

L Chen, M Wang, Q Kang, W Tao, Pore scale study of multiphase multicomponent reactive transport during CO₂ dissolution trapping, *Advances in Water Resources*, 2018, 116, 208-218

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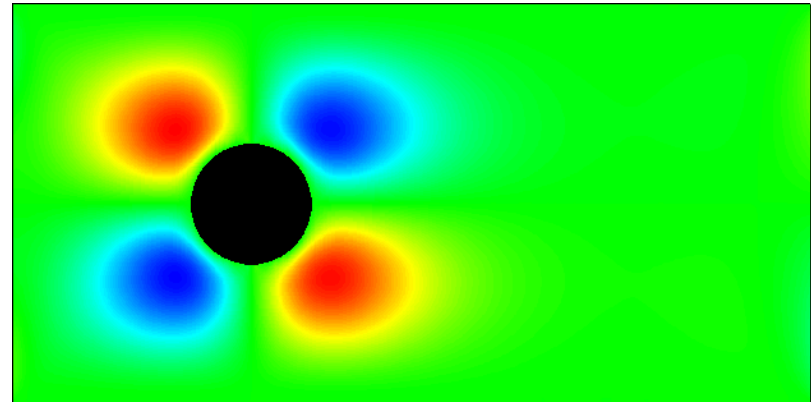
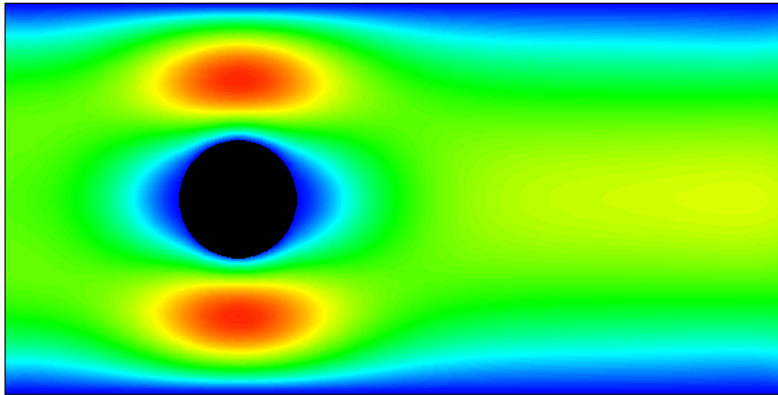
Case A: flow around a square



```

=====
SUBROUTINE SOLID_STRUCTURE
USE START_L
! Is represents the porous structure: 0 denotes nodes of void space, 1 denotes solid node.
Is=0
Is(:,ny:ny+1)=1
Is(:,0:1)=1
icenter=61
jcenter=ny/2+1
Is(icenter-15:icenter+15,jcenter-15:jcenter+15)=1
walls=.false.
do j=0,ny+1
do i=0,nx+1
if(Is(i,j).eq.1) then
walls(i,j)=.true.
endif
enddo
enddo
RETURN
END SUBROUTINE
=====
    
```


Case B: flow around a cylinder



```

SUBROUTINE SOLID_STRUCTURE
USE START_L
double precision::radius
! Is represents the porous structure: 0 denotes nodes of void space, 1 denotes solid node.
Is=0
Is(:,ny:ny+1)=1
Is(:,0:1)=1
icenter=61
jcenter=ny/2+1
walls=.false.
do j=0,ny+1
do i=0,nx+1
radius=sqrt(float(i-icenter)**2.+float(j-jcenter)**2.)
if(radius.le.15.d0) then
Is(i,j)=1
endif
if(Is(i,j).eq.1) then
walls(i,j)=.true.
endif
enddo
enddo
RETURN
END SUBROUTINE
    
```

!=====

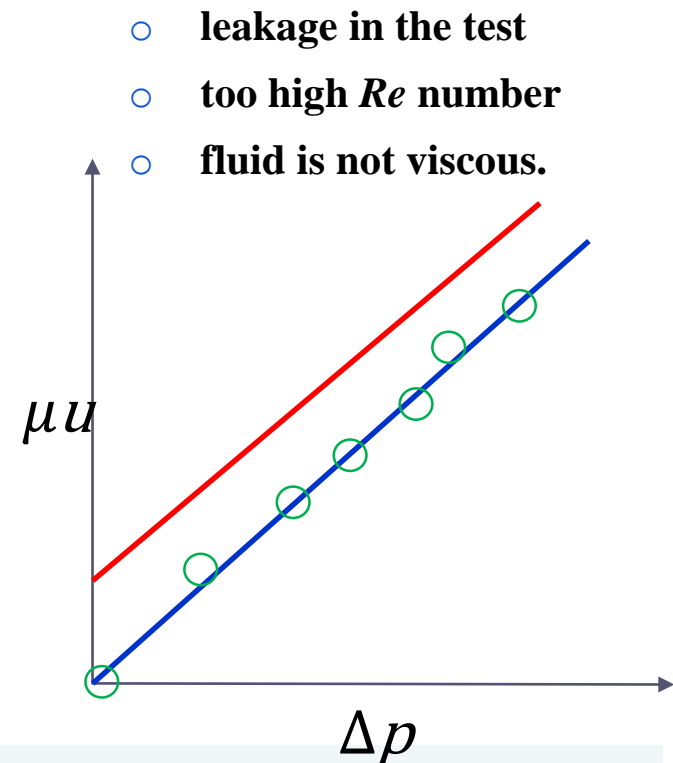
Permeability

- **Permeability**, an indicator of the capacity of a porous medium for fluid flow through

- In 1856, Darcy noted that for laminar flow through porous media, the flow rate $\langle u \rangle$ is linearly proportional to the applied pressure gradient Δp , he introduced **permeability to describe the conductivity of the porous media**. The Darcy' law is as follows

$$\langle u \rangle = - \frac{k}{\mu} \frac{\Delta p}{l}$$

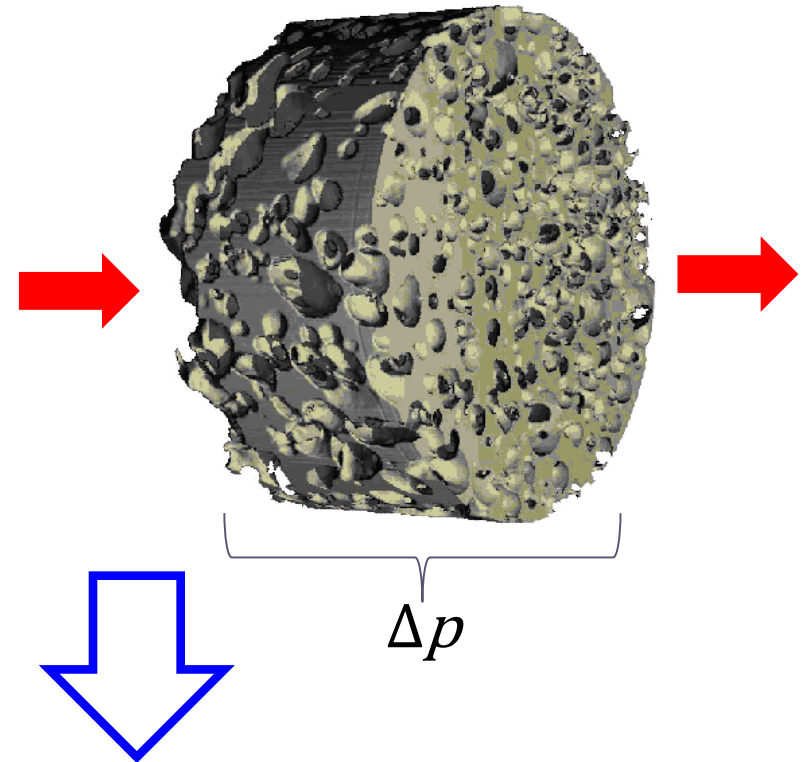
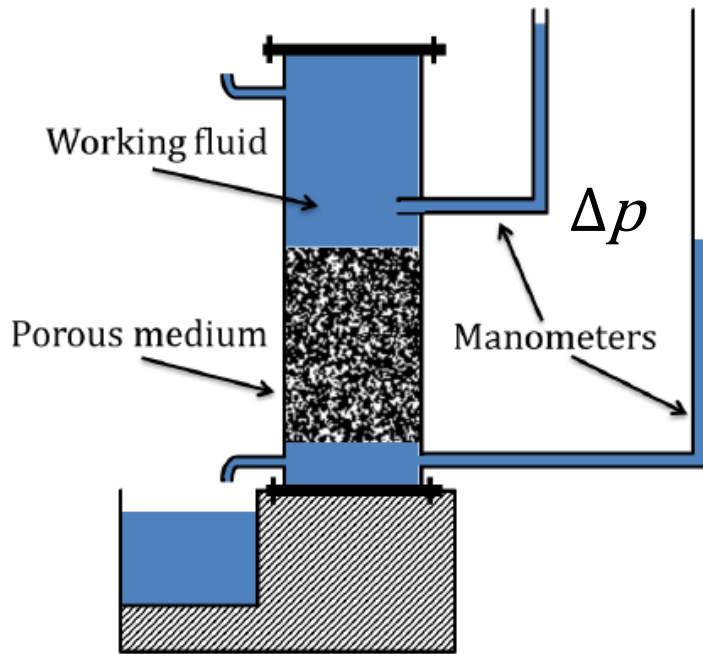
- q flow rate (m/s), μ the viscosity, pressure drop Δp , length of the porous domain l , **k is the permeability**.



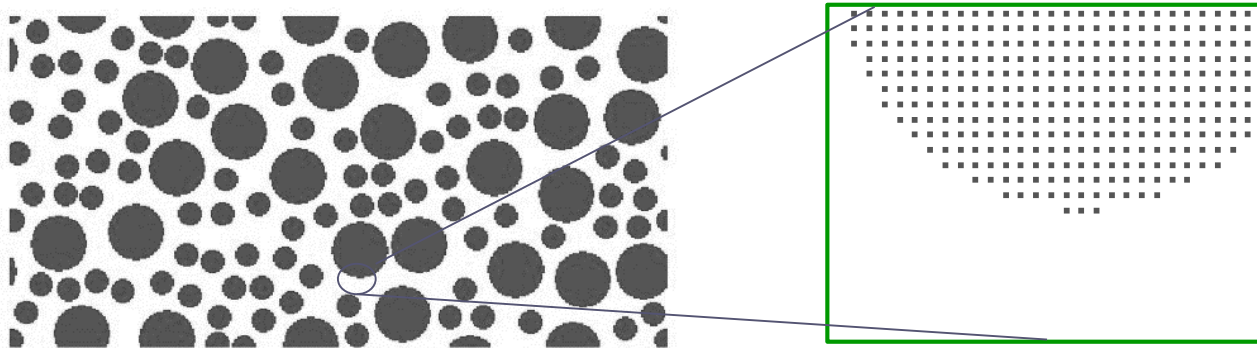
Pore-scale modeling of fluid flow

Schematic of Darcy's experiment

Simulation mimic the experiment



NS equation is solved at the pore scale. Non-slip boundary condition for the fluid-solid interface



Bounce-back at the solid surface

$$f_i(\mathbf{x} + \mathbf{c}_i \Delta t, t + \Delta t) - f_i(\mathbf{x}, t) = -\frac{1}{\tau} (f_i(\mathbf{x}, t) - f_i^{\text{eq}}(\mathbf{x}, t))$$

Collision

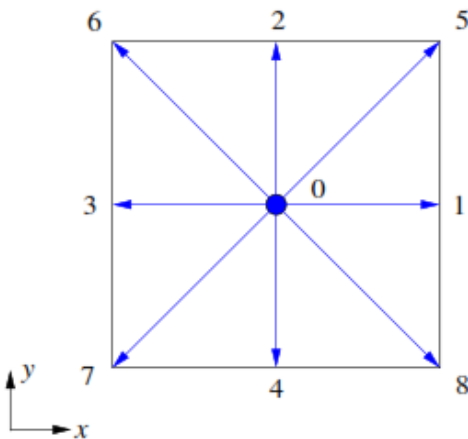
$$f'_i(\mathbf{x}, t) = -\frac{1}{\tau} (f_i(\mathbf{x}, t) - f_i^{\text{eq}}(\mathbf{x}, t))$$

Streaming

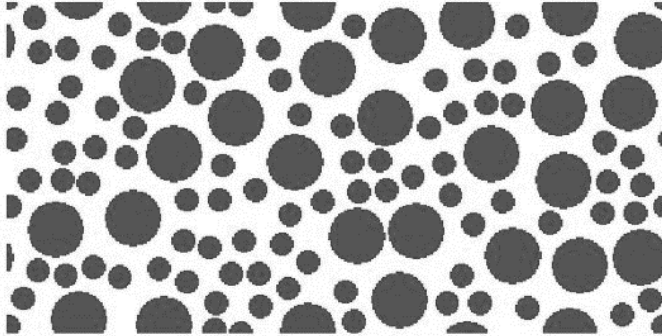
$$f_i(\mathbf{x} + \mathbf{c}_i \Delta t, t + \Delta t) = f'_i(\mathbf{x}, t)$$

Macroscopic variables calculation

$$\rho = \sum_{i=0} f_i, \quad \rho \mathbf{u} = \sum_{i=0} f_i \mathbf{e}_i.$$



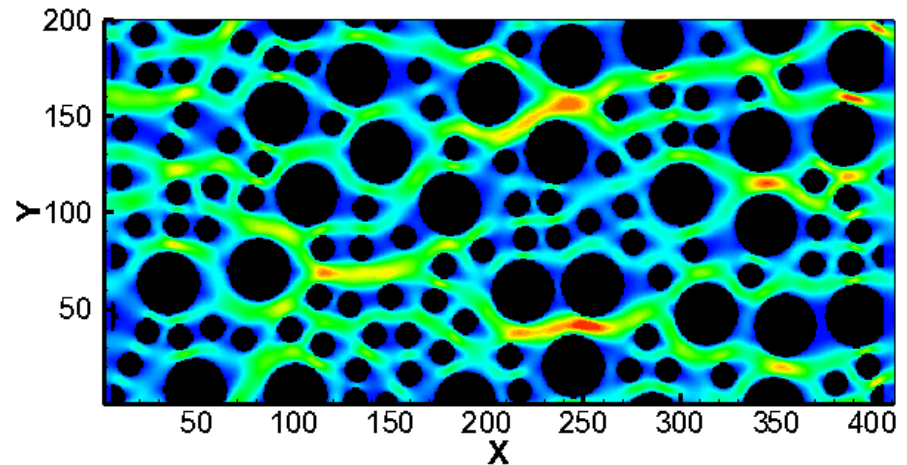
Pore-scale fluid flow in a 2D porous structure



- ◆ Bounce-back at the solid surface
- ◆ Pressure drop across x direction
- ◆ Periodic boundary condition y

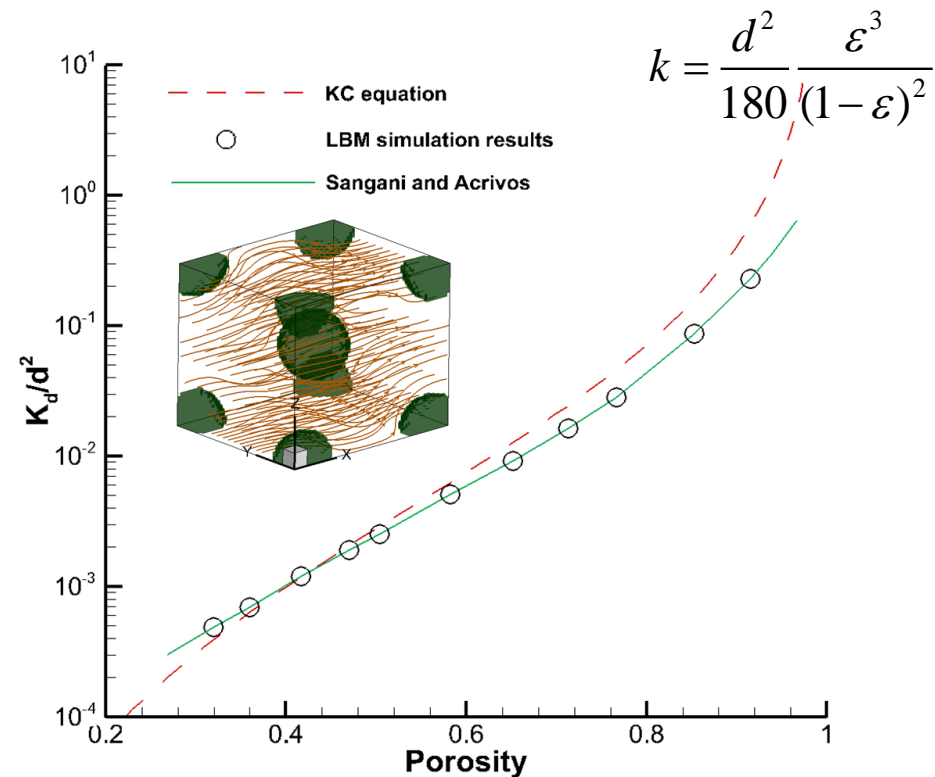
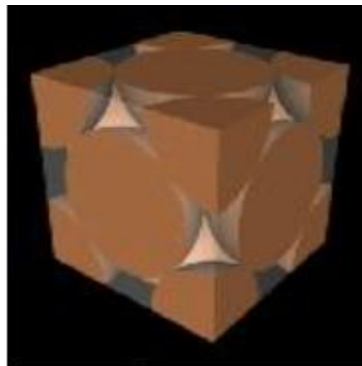
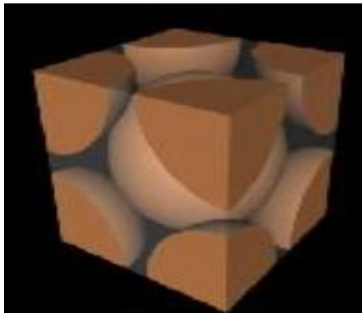
- ◆ Analyze the detailed flow field
- ◆ Calculate permeability based on Darcy equation.

$$\langle u \rangle = - \frac{k}{\mu} \frac{\Delta p}{l}$$



Permeability

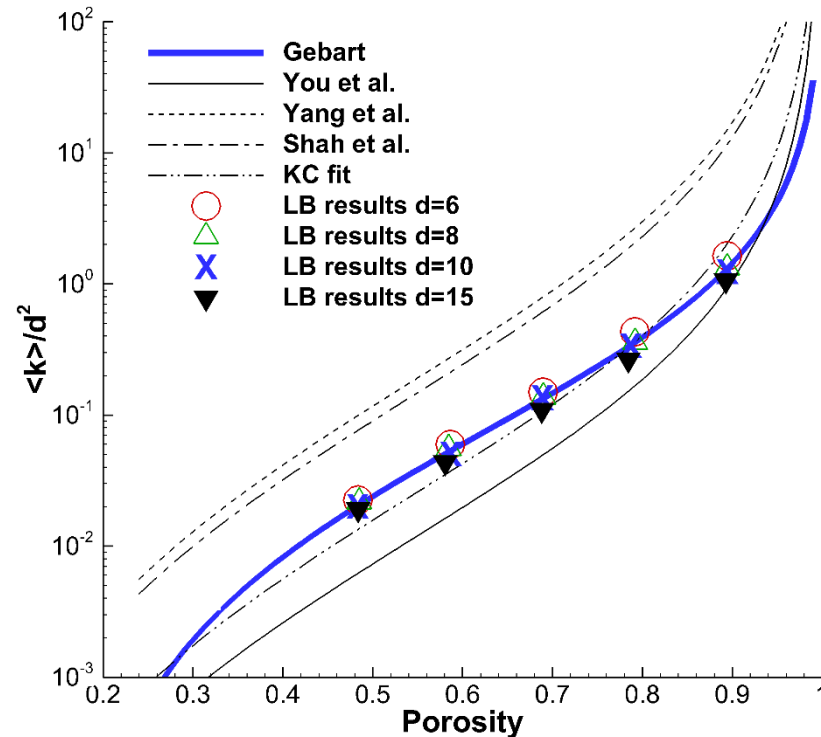
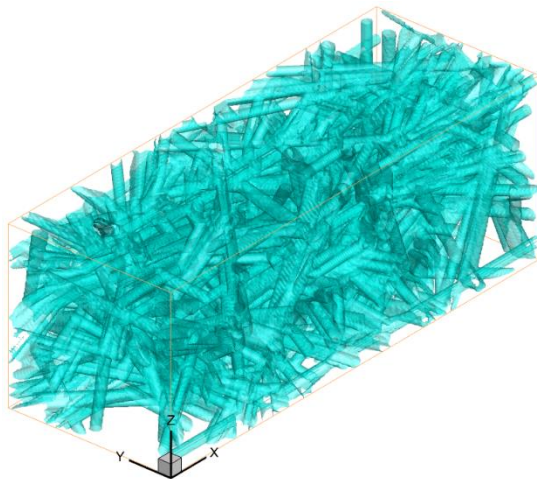
- One of the most famous empirical relationship between permeability and statistical structural parameters is proposed by Kozeny and Carman (KC) equation for beds of particle



Permeability

- Fibrous beds have received special attention for its wide applications such as filter which can form stable structures of very high porosity.

$$k = r^2 A \left(\sqrt{\frac{1 - \varepsilon_c}{1 - \varepsilon}} - 1 \right)^B$$



- L Chen, YL He, WQ Tao, P Zelenay, R Mukundan, Q Kang, Pore-scale study of multiphase reactive transport in fibrous electrodes of vanadium redox flow batteries, , Electrochimica Acta 248, 425-439;
- L. Chen*, H.B. Luan, Y.-L. He, W.-Q. Tao, Pore-scale flow and mass transport in gas diffusion layer of proton exchange membrane fuel cell with interdigitated flow fields, 2012, 51, 132-144, International journal of thermal science

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LB model for heat transfer

Evolution equation

$$g_i(\mathbf{x} + \mathbf{c}_i \Delta t, t + \Delta t) - g_i(\mathbf{x}, t) = -\frac{1}{\tau} (g_i(\mathbf{x}, t) - g_i^{eq}(\mathbf{x}, t)) + \omega_i S(\mathbf{x}, t)$$

Equilibrium distribution function

$$g_i^{eq} = \omega_i T (1 + 3\mathbf{c}_i \cdot \mathbf{u})$$

Temperature

$$T = \sum_i g_i$$

Thermal diffusivity

$$\alpha = \frac{\lambda}{\rho C_p} = \frac{1}{3} (\tau - 0.5) \frac{(\Delta x)^2}{\Delta t}$$

LB model for heat transfer

Standard energy governing equation

$$\frac{\partial(\rho c_p T)}{\partial t} + \nabla \cdot (\rho c_p \mathbf{u} T) = \nabla \cdot (\lambda \nabla T) + S$$

Energy equation recovered from LB

$$\frac{\partial(\rho c_p T)}{\partial t} + \nabla \cdot (\rho c_p \mathbf{u} T) = \nabla \cdot (\alpha \nabla \rho c_p T) + S$$

where

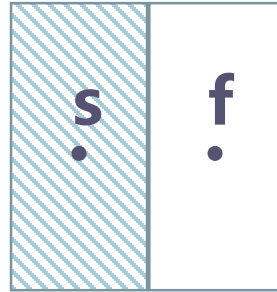
$$\alpha = \lambda / \rho c_p$$

thermal diffusivity of the material.

At the fluid-solid interface

$$T_f = T_s$$

$$-\lambda_f \frac{\partial(T)_f}{\partial n_f} = \lambda_s \frac{\partial(T)_s}{\partial n_s}$$



$$T_f = T_s$$

$$-\alpha_f \frac{\partial(\rho C_P T)_f}{\partial n_f} = \alpha_s \frac{\partial(\rho C_P T)_s}{\partial n_s}$$

Conjugate heat transfer

In LB

Satisfy Dirichlet- and Neumann-like boundary restriction at the same time

Only when heat capacity of the two materials is the same, the conjugate heat transfer condition form the LB is equal to practical case!

Heat conduction across two solids

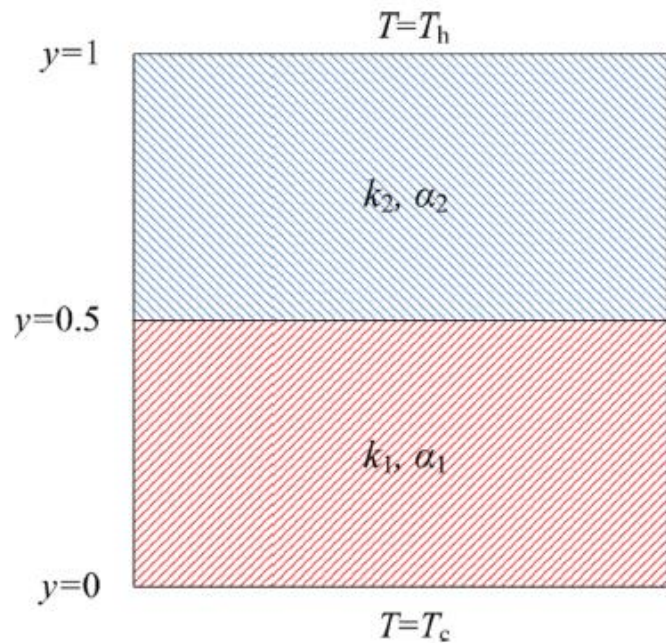


FIG. 1. (Color online) Schematic of two-layer stratified medium.

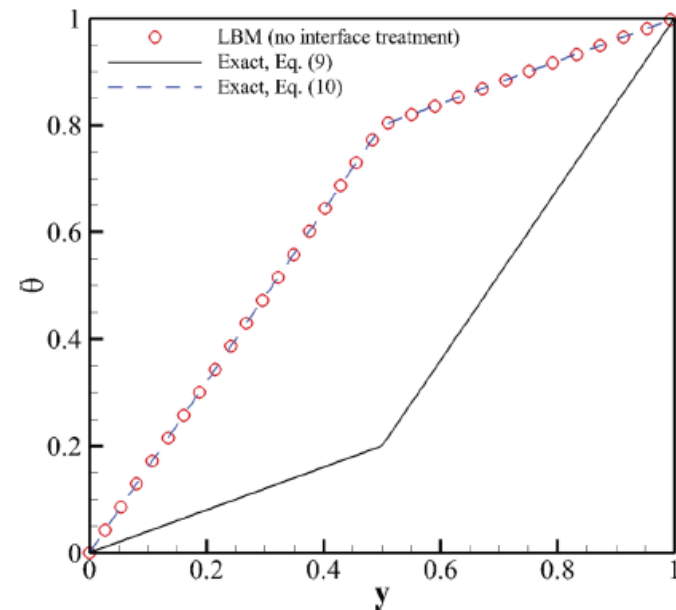


FIG. 2. (Color online) Comparison of LBM solution with analytical solutions for two-layered stratified medium.

$$\frac{\lambda_1}{\lambda_2} = 4$$

$$\frac{\alpha_1}{\alpha_2} = 4$$

LB model for predicting thermal conductivity

Standard energy governing equation

$$\frac{\partial(\rho c_p T)}{\partial t} + \nabla \cdot (\rho c_p \mathbf{u} T) = \nabla \cdot (\lambda \nabla T) + S$$

$$\mathbf{f} \quad \nabla \cdot (\rho c_p \mathbf{u} T) = \nabla \cdot (\lambda \nabla T)$$

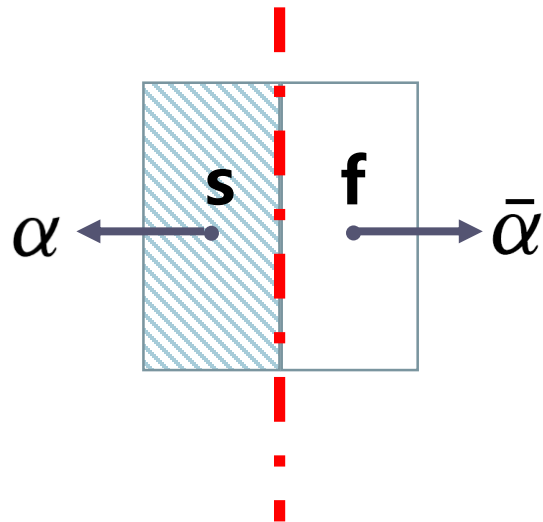
$$\mathbf{s} \quad 0 = \nabla \cdot (\lambda \nabla T)$$

“pseudo-capacity of solid phase” scheme

$$(\rho c_p)_f = (\rho c_p)_s$$

$$\mathbf{s} \quad 0 = \nabla \cdot \left(\frac{\lambda_s}{(\rho c_p)_f} \nabla T \right)$$

$$\frac{\alpha_f}{\alpha_s} = \frac{\lambda_f}{\lambda_s}$$



$$g_{\bar{\alpha}}(\mathbf{x}_f, t + \delta t) = \hat{g}_{\bar{\alpha}}(\mathbf{x}_s, t),$$

$$g_{\alpha}(\mathbf{x}_s, t + \delta t) = \hat{g}_{\alpha}(\mathbf{x}_f, t)$$

Half lattice node

$$g_{\alpha}(\mathbf{r} + \mathbf{e}_{\alpha} \delta t) - g_{\alpha}(\mathbf{r}, t) = -\frac{1}{\tau_g} [g_{\alpha}(\mathbf{r}, t) - g_{\alpha}^{\text{eq}}(\mathbf{r}, t)]$$

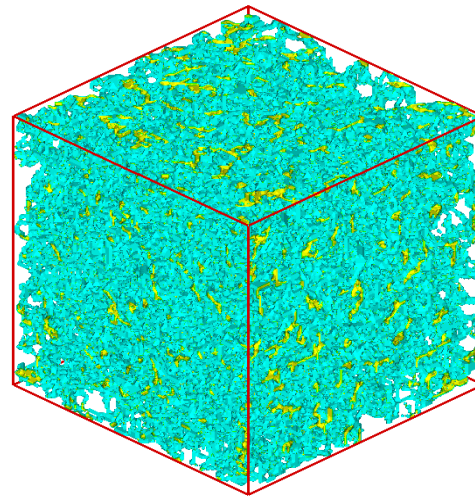
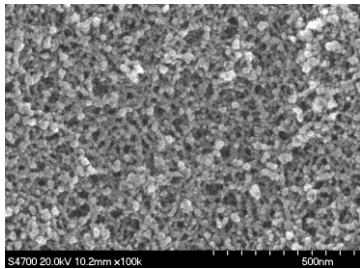
$$\tau_g = \frac{3}{2} \frac{\lambda}{\rho c_p c^2 \delta t} + 0.5$$

$$T = \sum_{\alpha} g_{\alpha}$$

Prediction of thermal conductivity of aerogel



Aerogel: low density and k



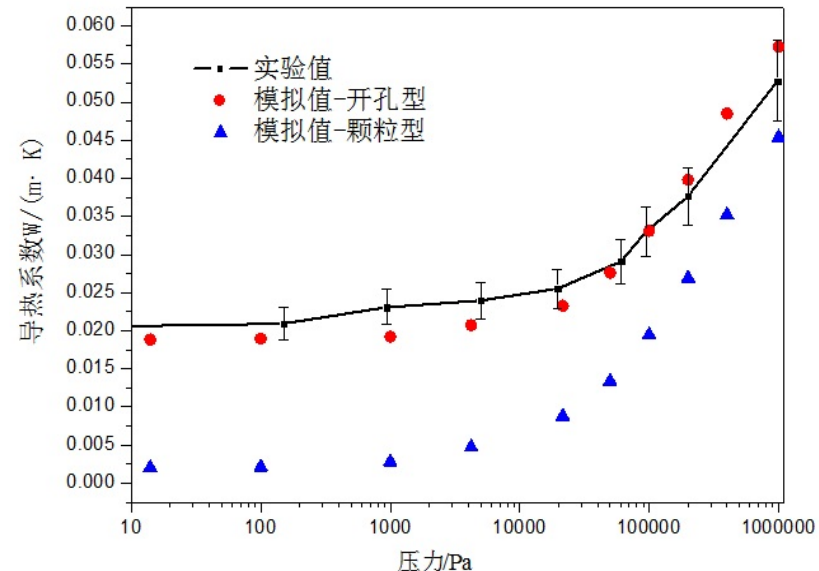
Different components with Large variations of k



$$\lambda_{x,e} = \frac{\int q_x dA_x}{(\Delta T/L_x)A_x}$$

$$\lambda_{y,e} = \frac{\int q_y dA_y}{(\Delta T/L_y)A_y}$$

$$\lambda_{z,e} = \frac{\int q_z dA_z}{(\Delta T/L_z)A_z}$$



Effective thermal conductivity

General case

For general heat transfer process, the unsteady term should be considered, and thus the “pseudo-capacity of solid phase scheme” fails.

1. Treat the interface as boundary

Treat the interface as boundary. Then the problem is changed to construct boundary condition at the phase interface.

2. Re-arrange the governing equation

Re-arrange the energy equation and add additional source term into the governing equation.

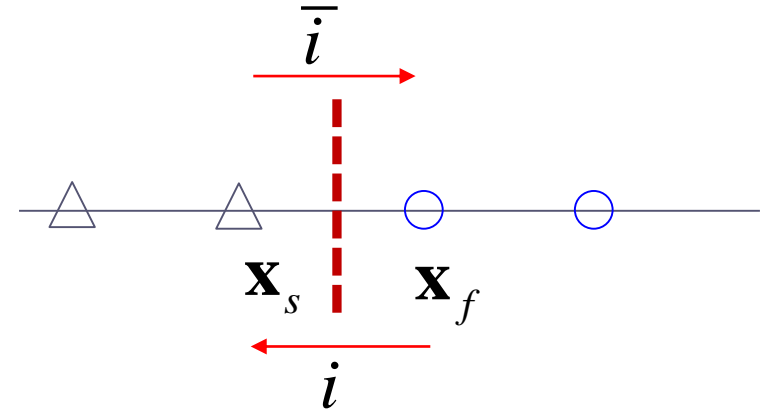
1. Treat the interface as boundary

Dirichlet condition

$$g_{\bar{i}}(\mathbf{x}_f, t + \Delta t) = -\hat{g}_i(\mathbf{x}_f, t) + \varepsilon_D \phi_d$$

Neumann equation

$$g_{\bar{i}}(\mathbf{x}_f, t + \Delta t) = \hat{g}_i(\mathbf{x}_f, t) + \frac{\Delta t}{\Delta x} J_d$$



$$g_{\bar{i}}(\mathbf{x}_f, t + \Delta t) = \left(\frac{1-\sigma}{1+\sigma}\right)\hat{g}_i(\mathbf{x}_f, t) + \left(\frac{2\sigma}{1+\sigma}\right)\hat{g}_{\bar{i}}(\mathbf{x}_s, t)$$

$$\sigma = \frac{(\rho C_p)_s}{(\rho C_p)_f}$$

$$g_i(\mathbf{x}_s, t + \Delta t) = -\left(\frac{1-\sigma}{1+\sigma}\right)\hat{g}_{\bar{i}}(\mathbf{x}_s, t) + \left(\frac{2}{1+\sigma}\right)\hat{g}_i(\mathbf{x}_f, t)$$

2. Re-arrange the governing equation

$$\frac{\partial(\rho c_p T)}{\partial t} + \nabla \cdot (\rho c_p \mathbf{u} T) = \nabla \cdot (\lambda \nabla T) + S$$

$$\frac{\partial(\rho c_p T)}{\partial t} + \nabla \cdot (\rho c_p \mathbf{u} T) = \nabla \cdot \left(\frac{\lambda}{\rho c_p} \rho c_p \nabla \left(\frac{\rho c_p T}{\rho c_p} \right) \right) + S$$

$$\begin{aligned} \alpha \rho c_p \nabla \left(\frac{h}{\rho c_p} \right) &= \alpha \rho c_p \left(\frac{1}{\rho c_p} \nabla h + h \nabla \frac{1}{\rho c_p} \right) \\ &= \alpha \nabla h + \alpha \rho c_p h \nabla \frac{1}{\rho c_p} \end{aligned}$$

$$\frac{\partial(\rho c_p T)}{\partial t} + \nabla \cdot (\rho c_p \mathbf{u} T) = \nabla(\alpha \nabla h) + \nabla(\alpha \rho c_p h \nabla \frac{1}{\rho c_p}) + S$$

S*



同舟共济
渡彼岸!